

The Flow of Association and Causation in Graphs

Brady Neal

causalcourse.com

Graph terminology

Bayesian networks and causal graphs

The basic building blocks of graphs

The flow of association and causation

Graph terminology

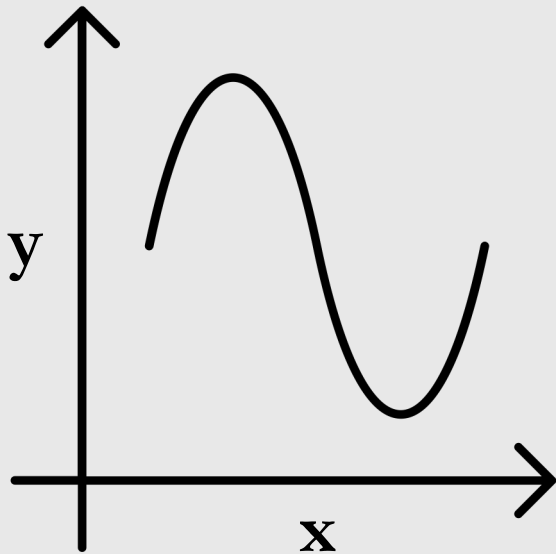
Bayesian networks and causal graphs

The basic building blocks of graphs

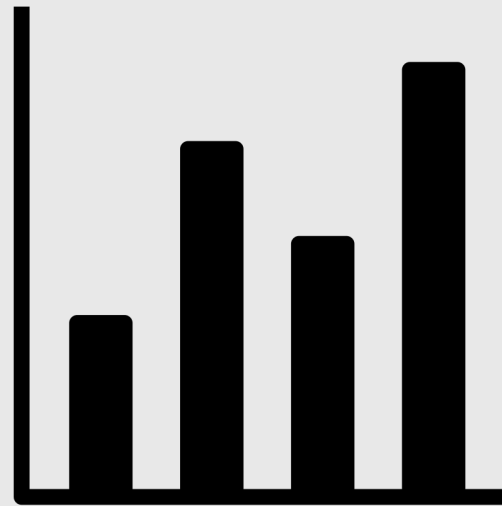
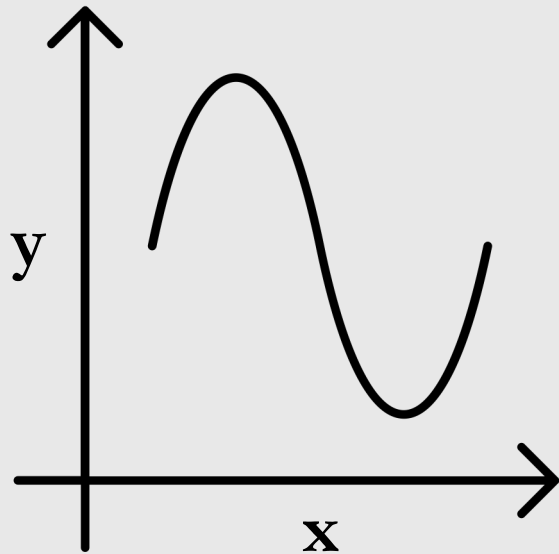
The flow of association and causation

Graph terminology: not a graph

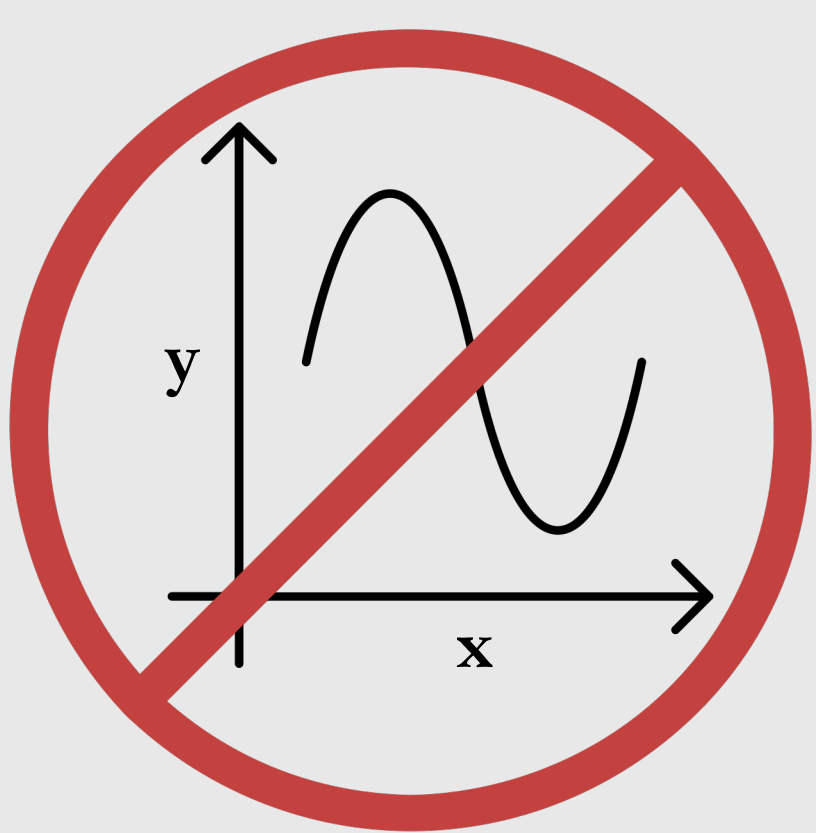
Graph terminology: not a graph



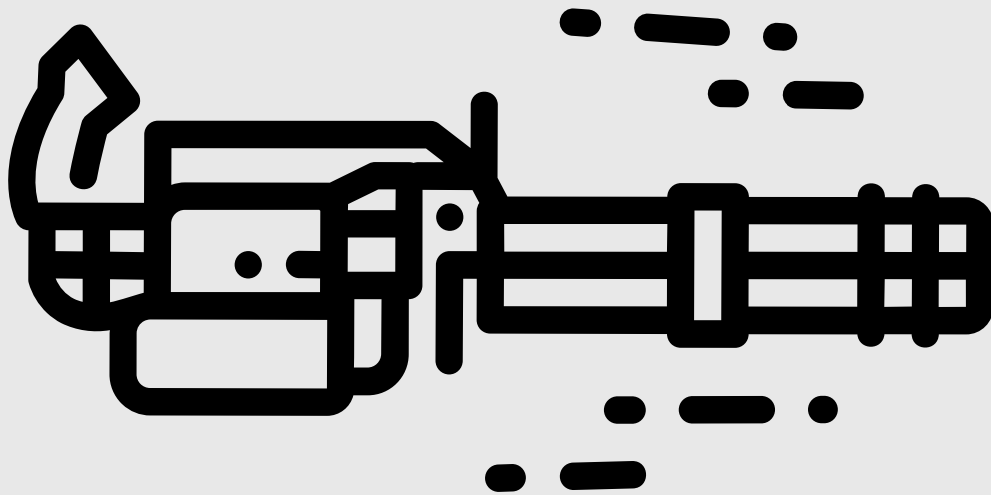
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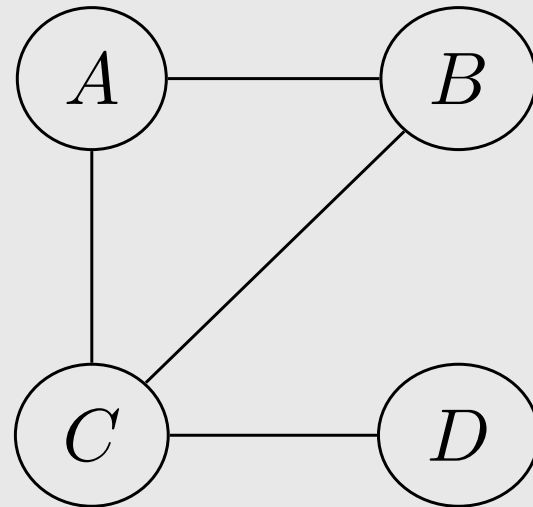
Graph terminology: Terminology Machine Gun



term term term
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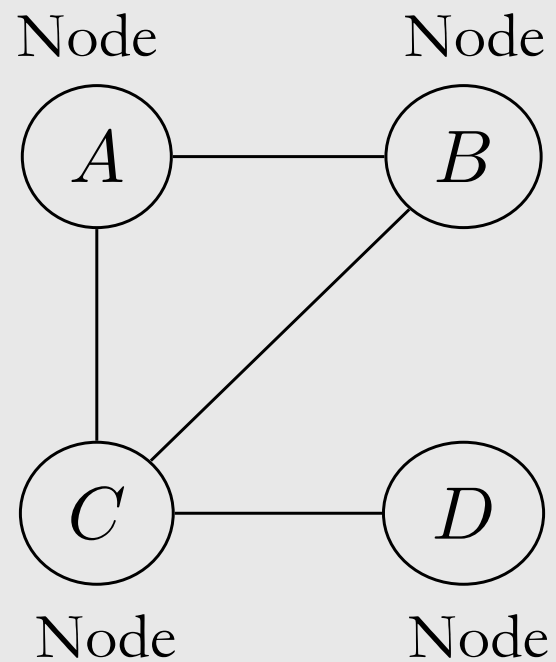
Graph terminology

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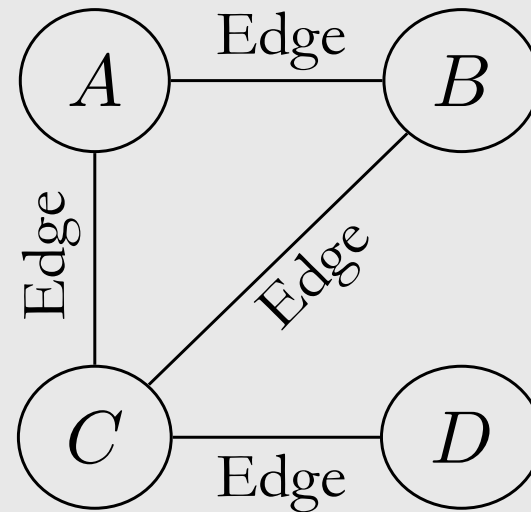
Graph terminology

Nodes



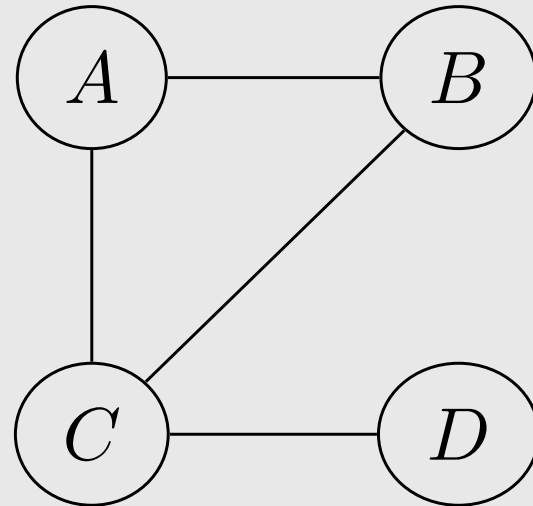
Graph terminology

Edges



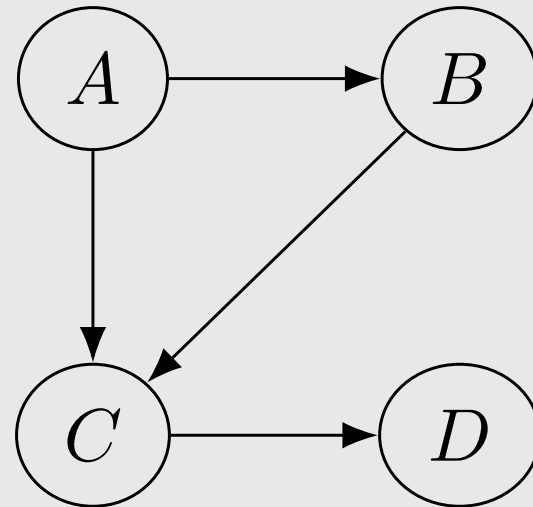
Graph terminology

Undirected
Graph



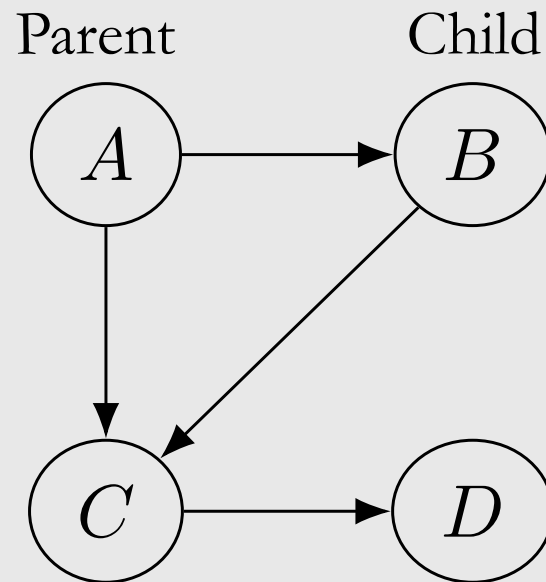
Graph terminology

Directed
Graph



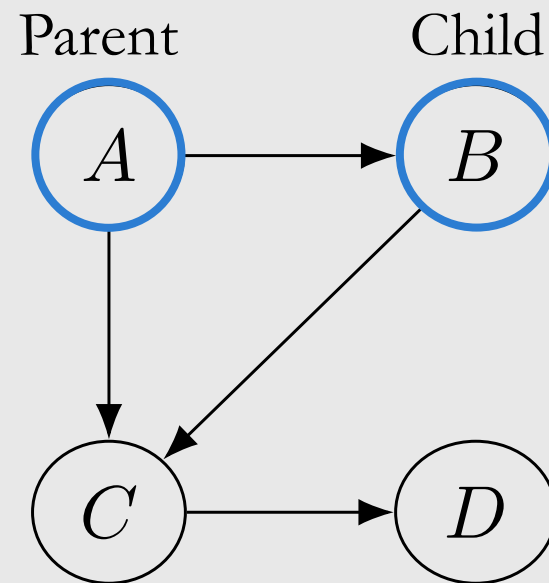
Graph terminology

Directed
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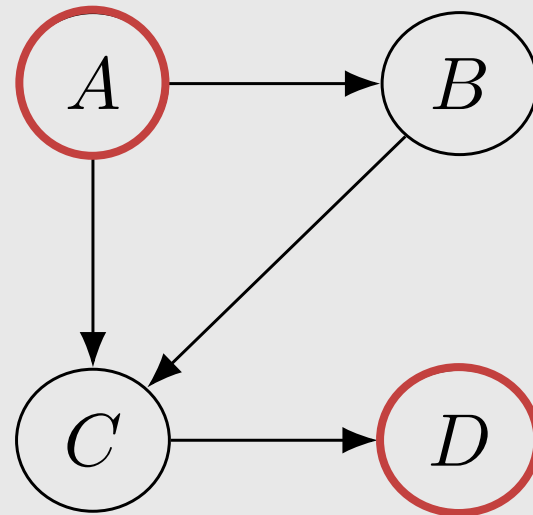
Graph terminology

Adjacent



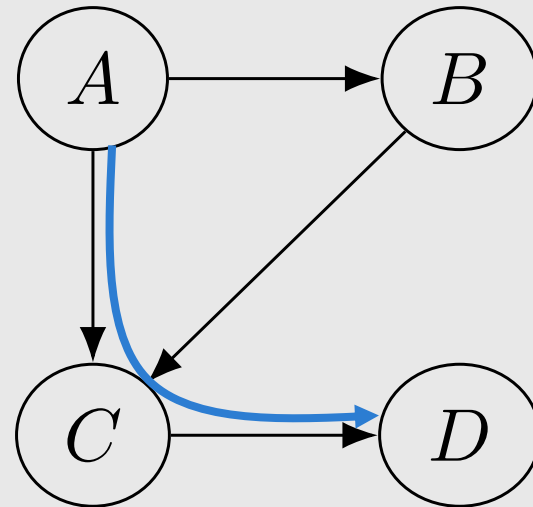
Graph terminology

Not
Adjacent



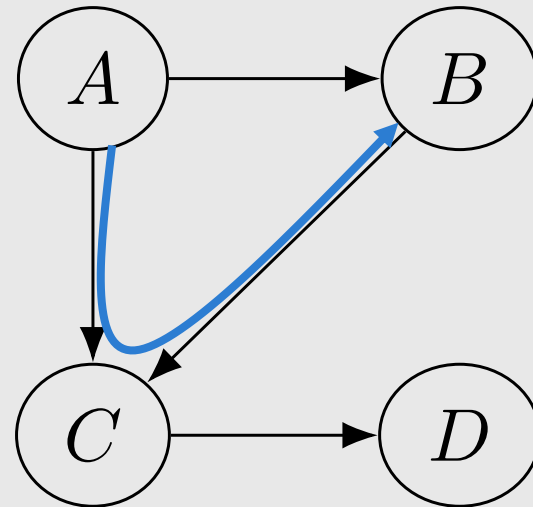
Graph terminology

Path



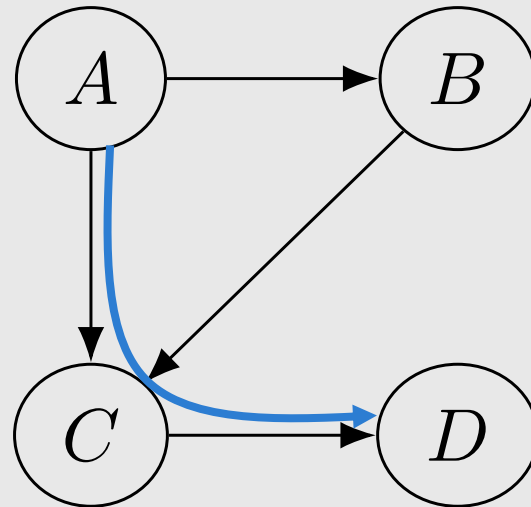
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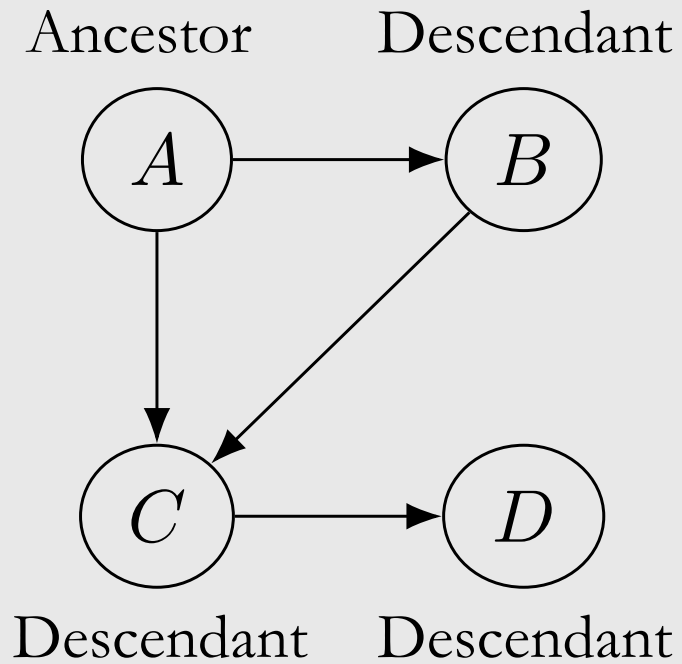


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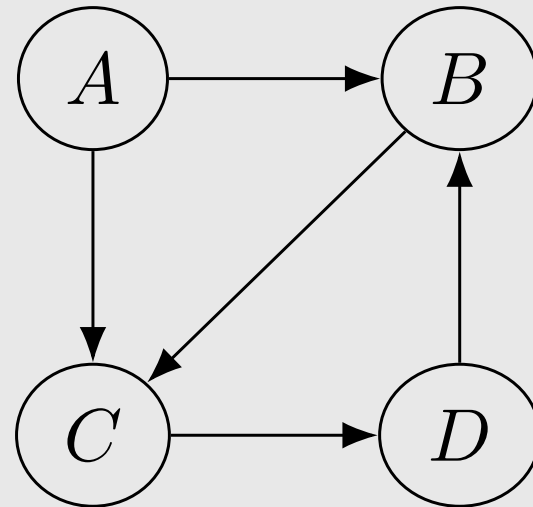
Directed
Path



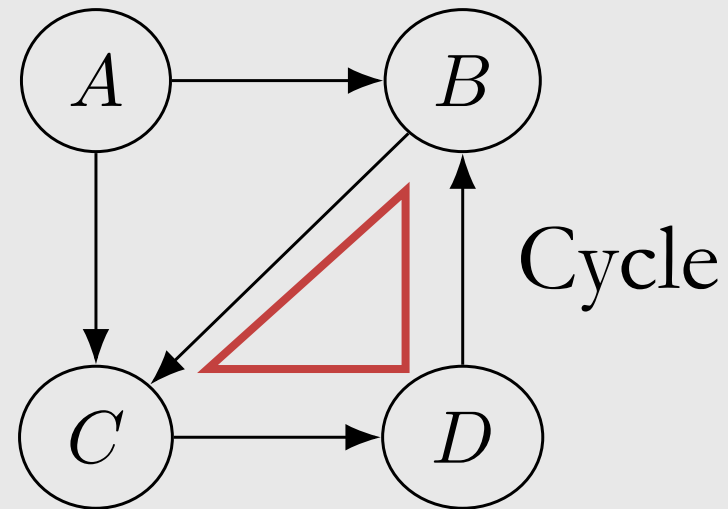
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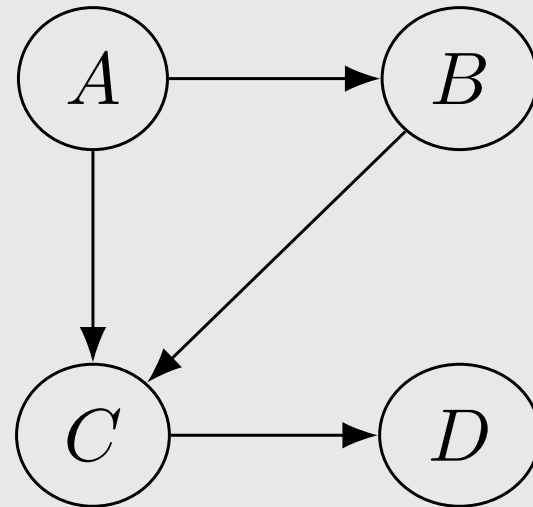
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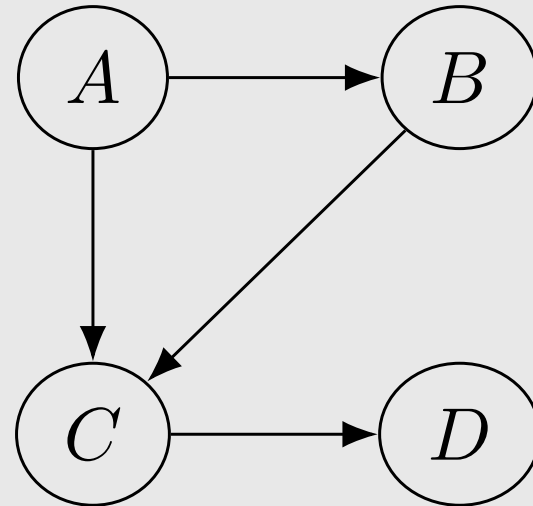


Graph terminology



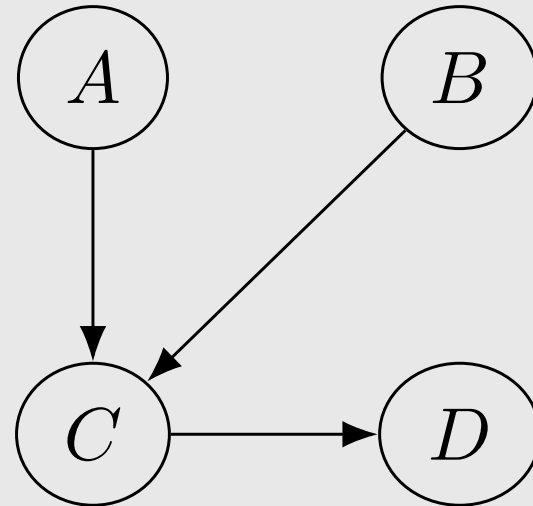
Graph terminology

Directed Acyclic
Graph (DAG)



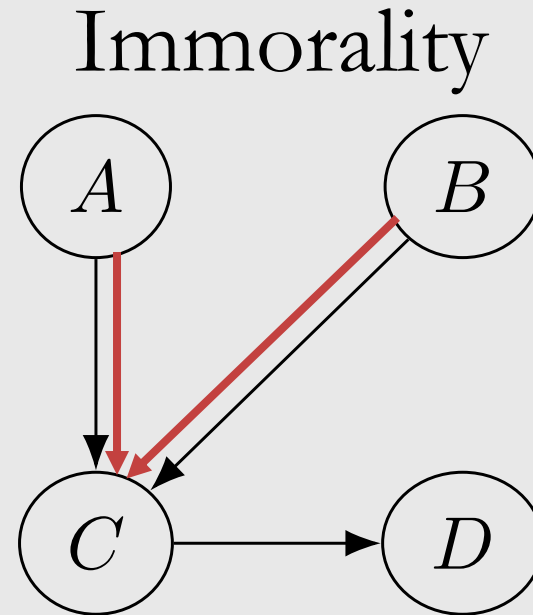
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Graph terminology

Bayesian networks and causal graphs

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The flow of association and causation

Naively modeling the joint distribution

Statistical modeling (no causality):

Naively modeling the joint distribution

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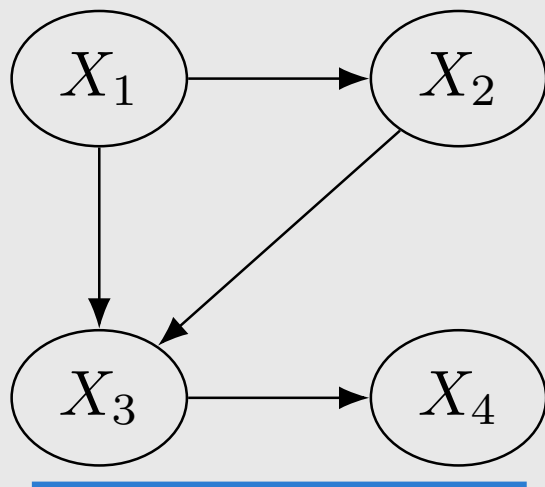
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2^{n-1} parameters!

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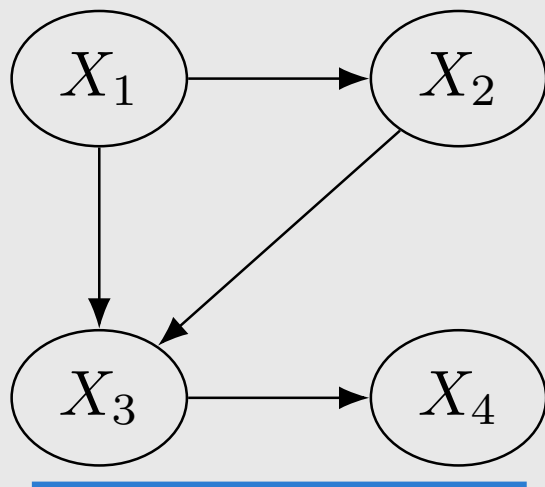
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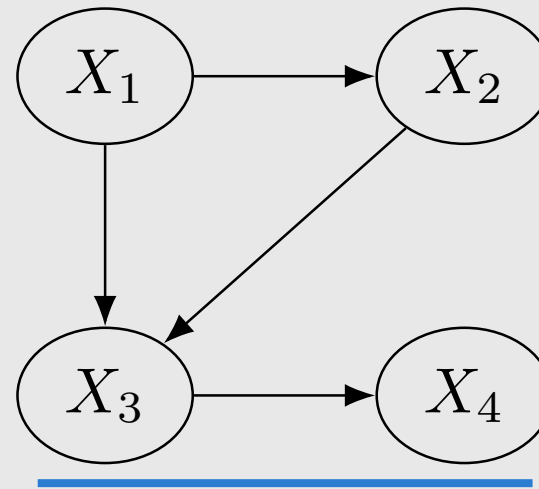
Local Markov assumption

Given its parents in the DAG, a node X is independent of all of its non-descendants.

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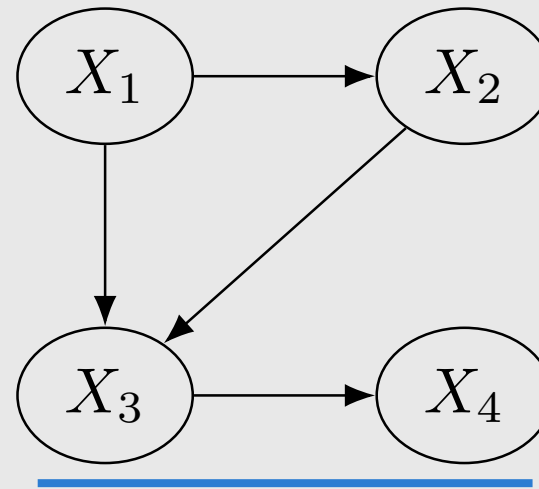
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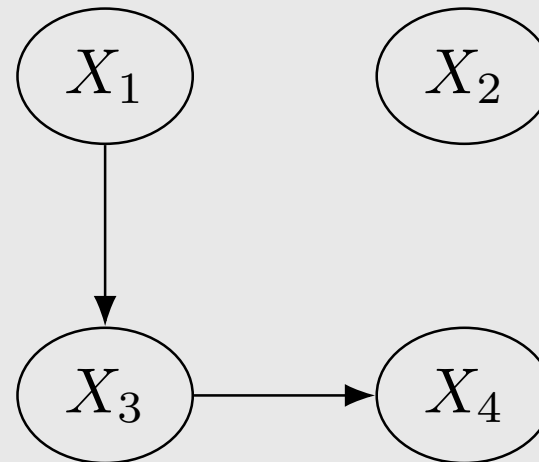
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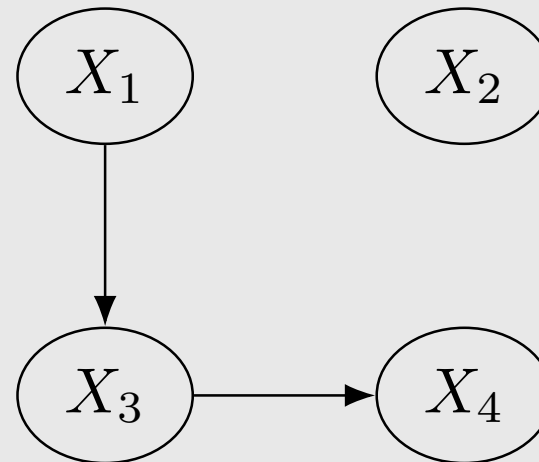
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Question:

How will the factorization change now?



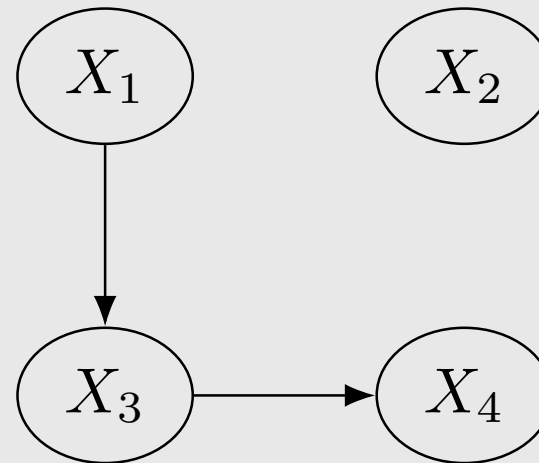
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Bayesian network factorization

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local Markov assumption \implies Bayesian network factorization

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local Markov assumption \impliedby Bayesian network factorization

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See Chapter 3 of [Koller & Friedman \(2009\) book](#) for proofs

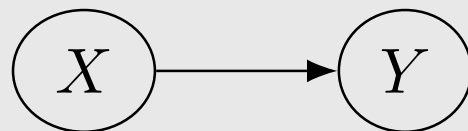
Minimality assumption

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1. Given its parents in the DAG, a node X is independent of all its non-descendants (local Markov assumption).

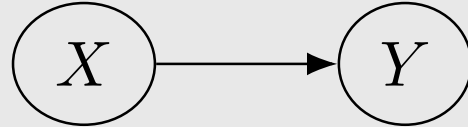
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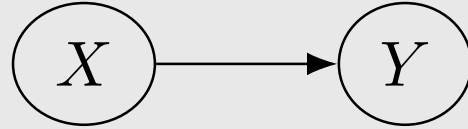
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Permits distributions where $P(x, y) = P(x) P(y | x)$

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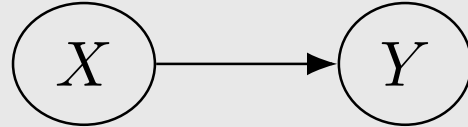


Permits distributions where $P(x, y) = P(x) P(y | x)$ and also where

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1. Given its parents in the DAG, a node X is independent of all its non-descendants (local Markov assumption).
2. Adjacent nodes in the DAG are dependent.

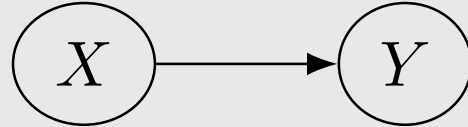


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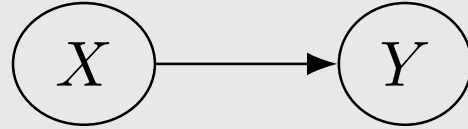


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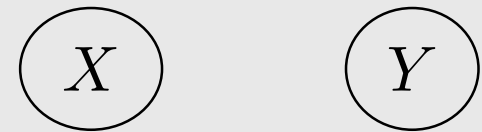
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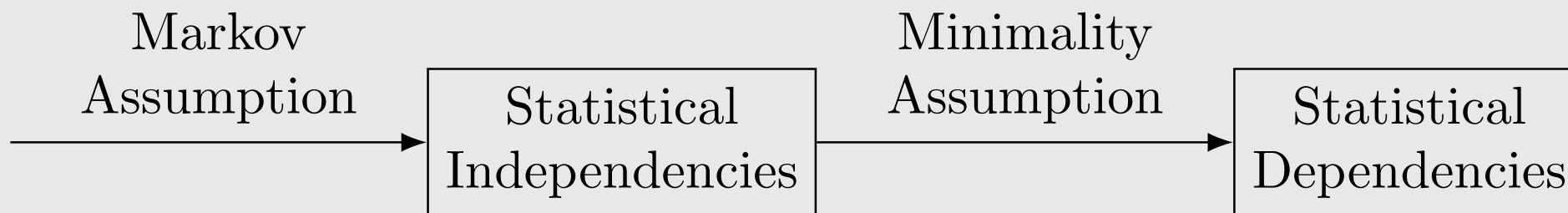


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Assumptions flowchart



Recall:

1. How is the local Markov assumption related to the Bayesian network factorization?
2. What are the two parts of the minimality assumption? What do we gain with the second part?

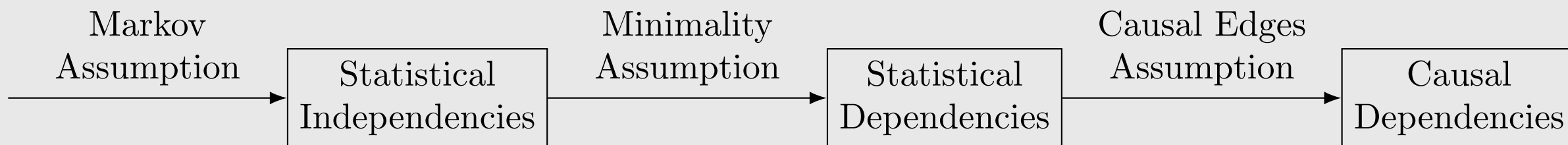
What is a cause?

A variable X is said to be a cause of a variable Y if Y can change in response to changes in X .

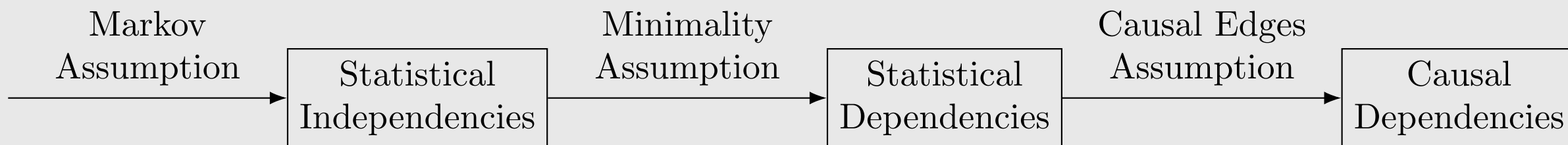
Causal edges assumption

In a directed graph, every parent is a direct cause of all its children.

Assumptions flowchart



Assumptions flowchart



DAG +

Two assumptions to give us flow of association and causation in graphs:

1. Markov Assumption
2. Causal Edges Assumption

Graph terminology

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The basic building blocks of graphs

The flow of association and causation

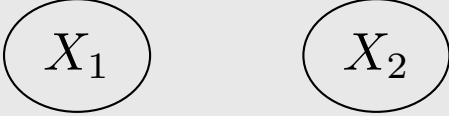
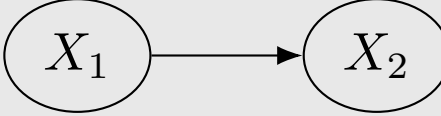
Graphical building blocks

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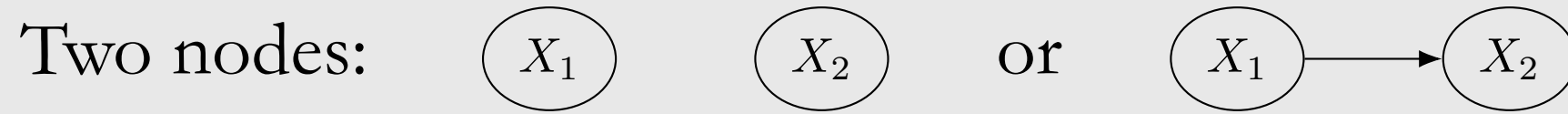
Two nodes: X_1 X_2



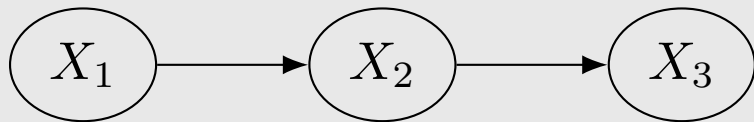
Graphical building blocks

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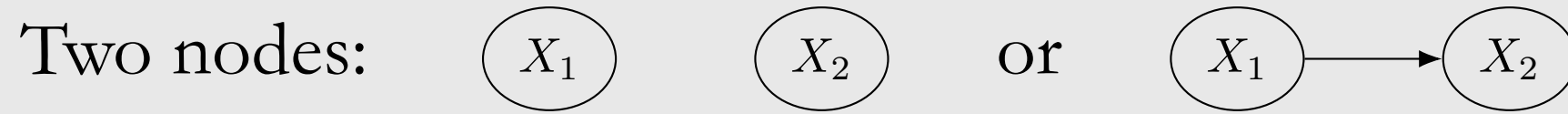
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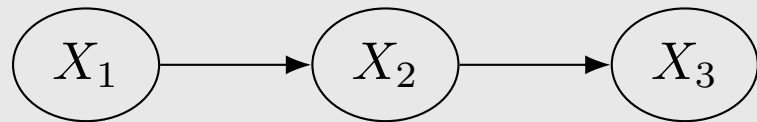
Chain



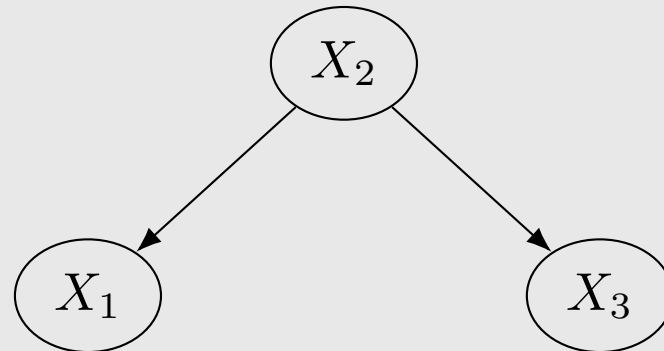
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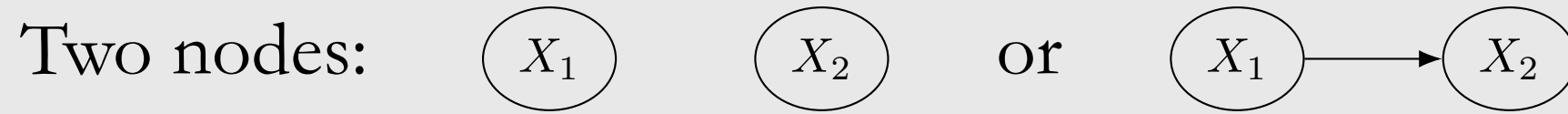
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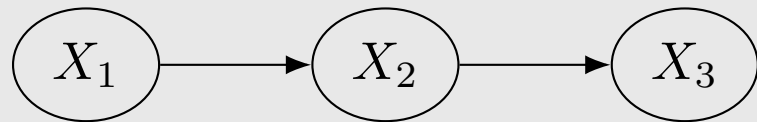
Fork



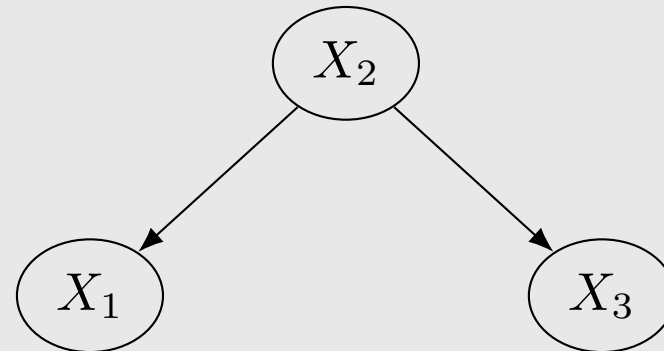
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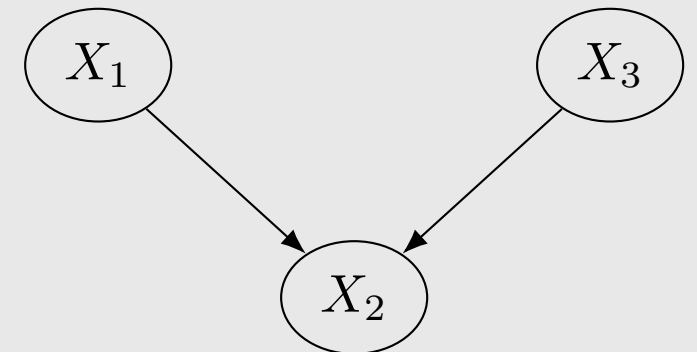
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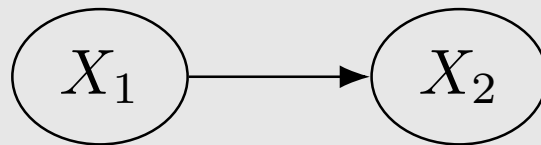


Immorality

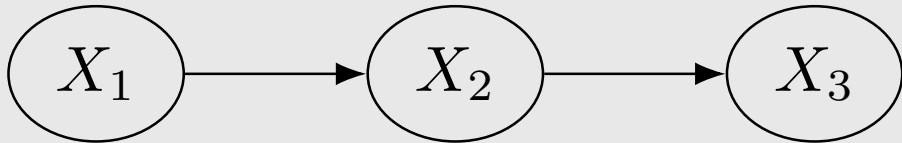


Question:

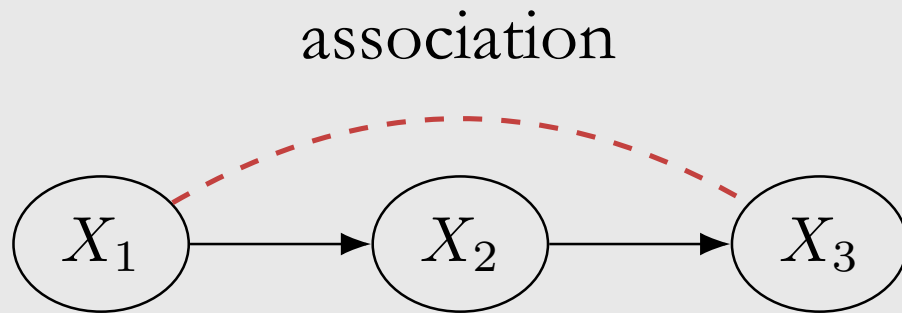
What assumption tells us that X_1 and X_2 are associated, given the following graph?



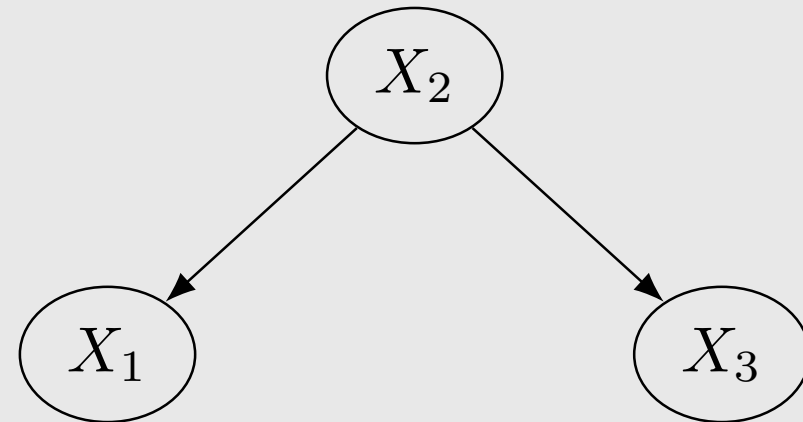
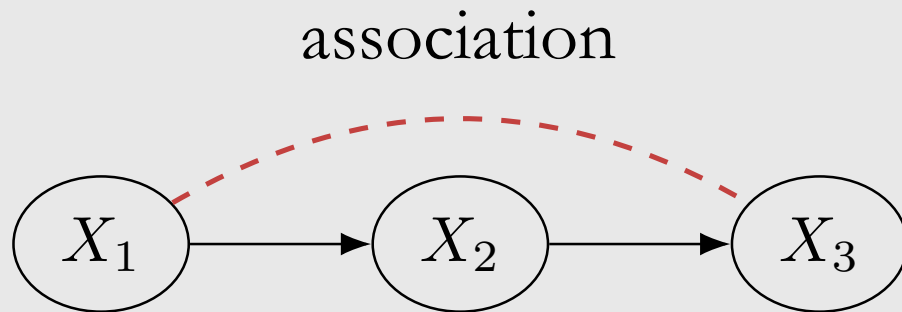
Chains and forks: dependence



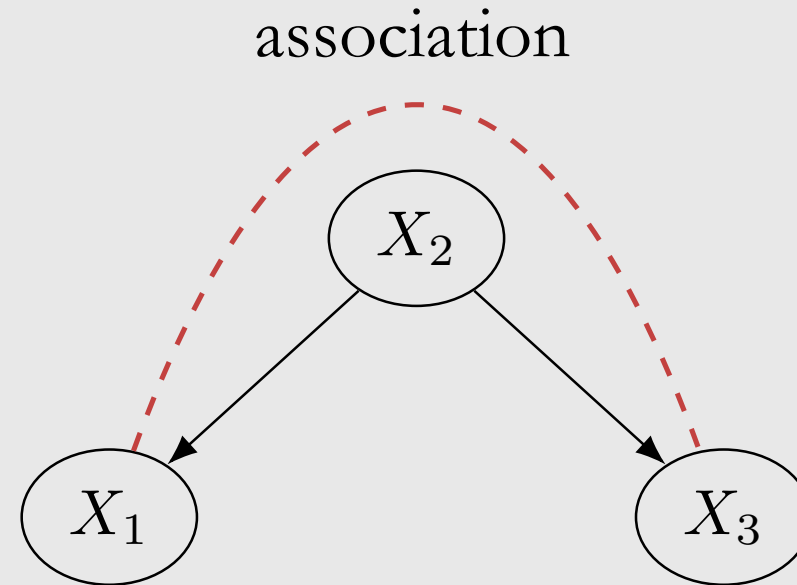
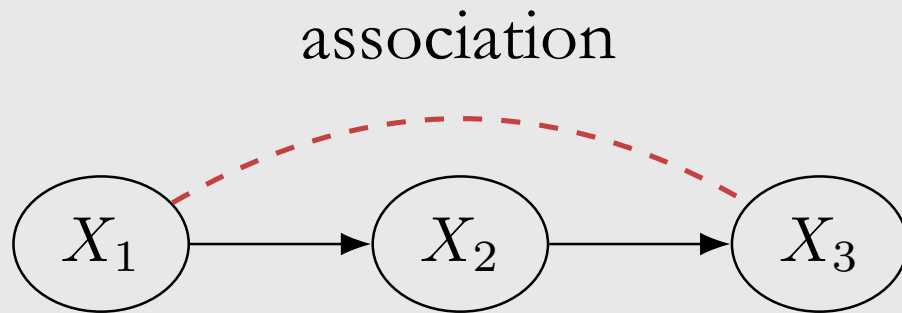
Chains and forks: dependence



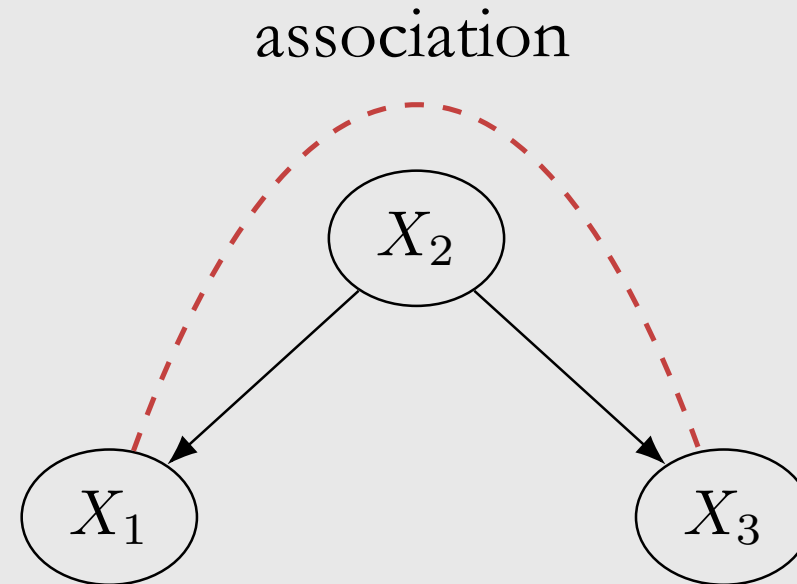
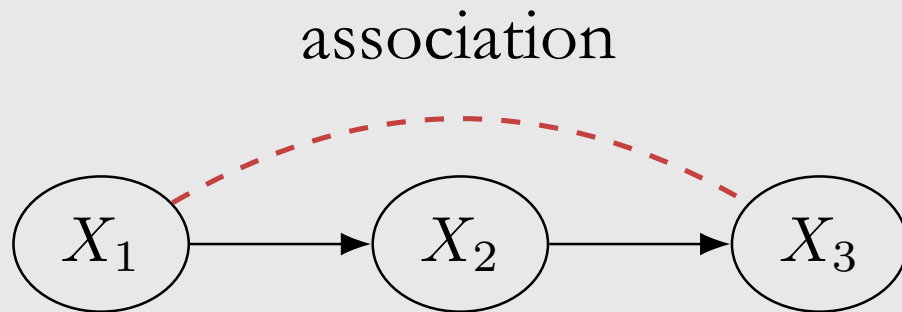
Chains and forks: dependence



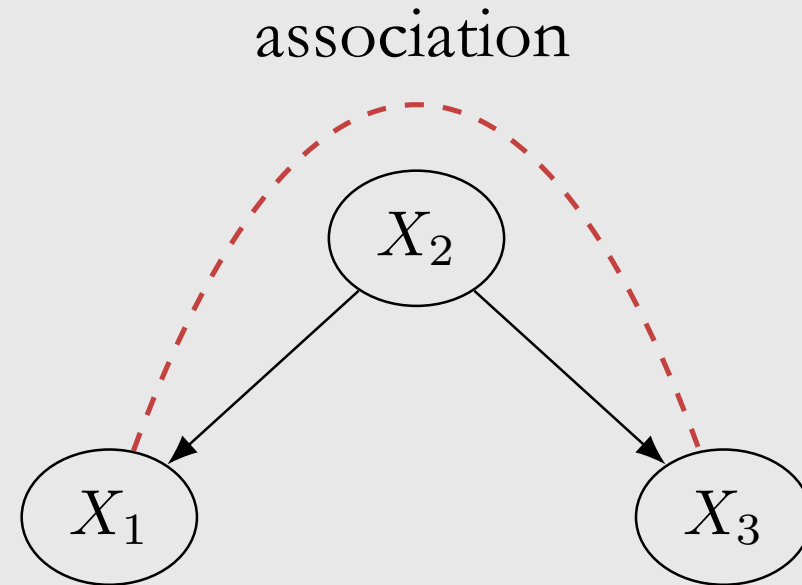
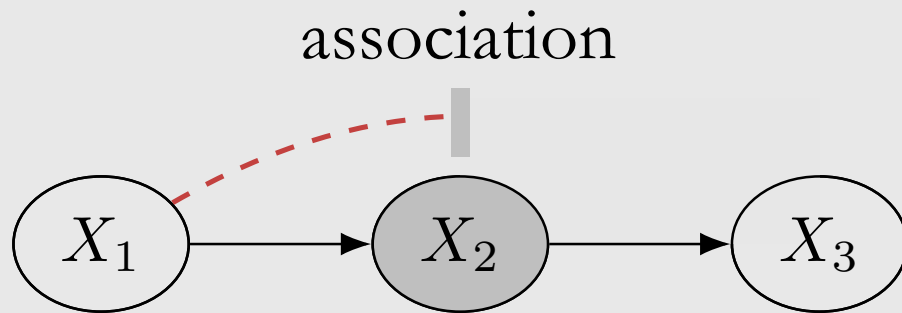
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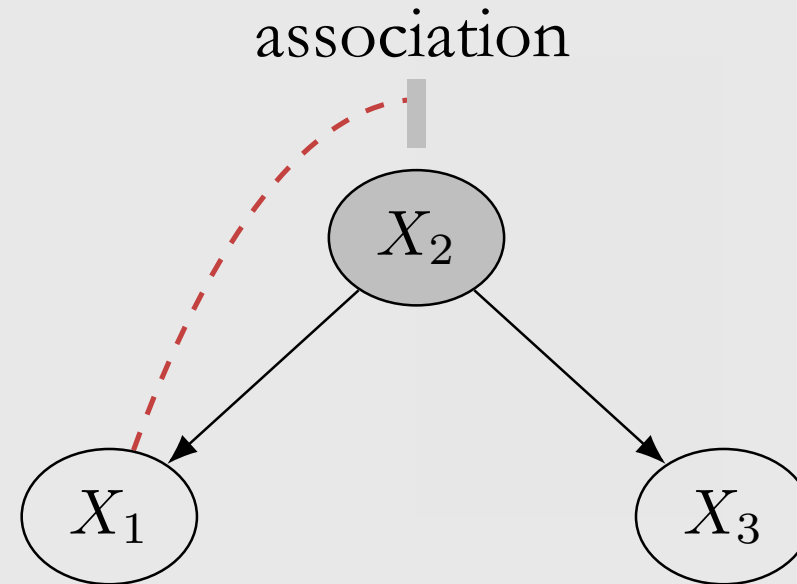
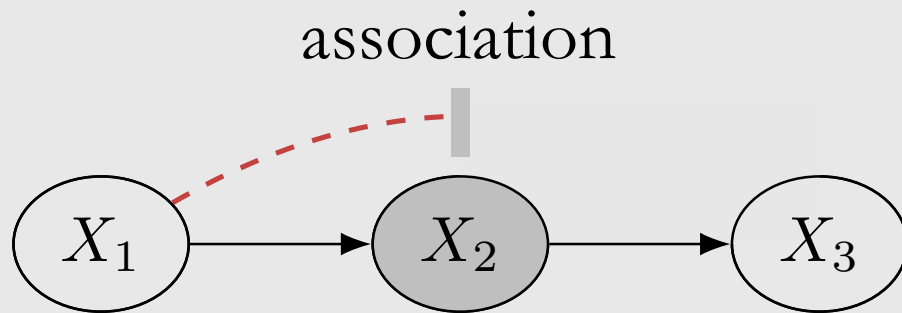
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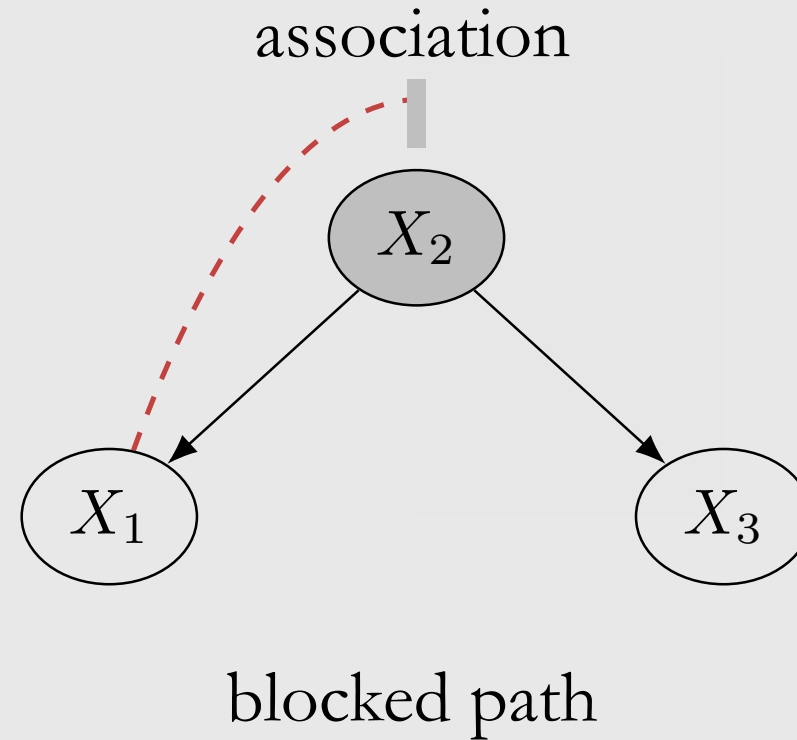
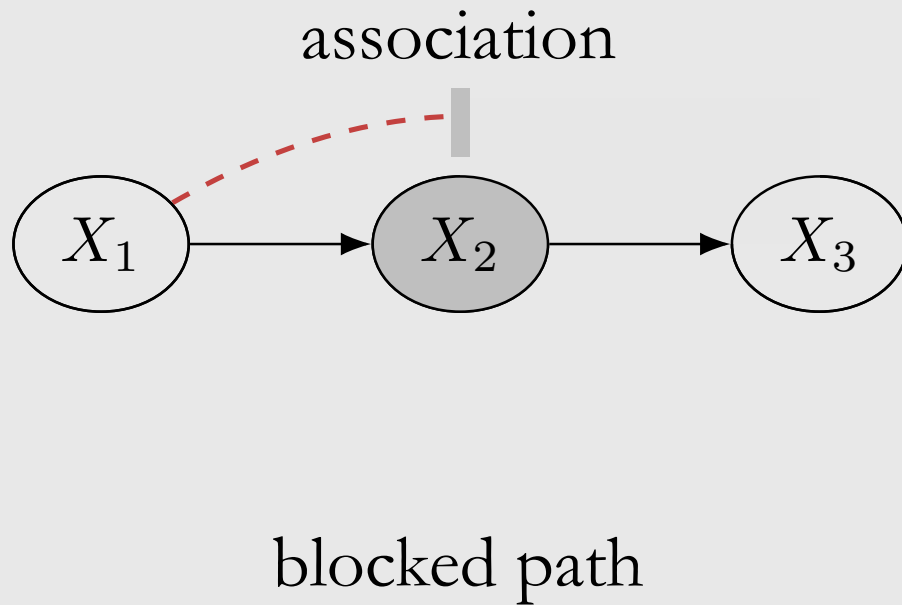
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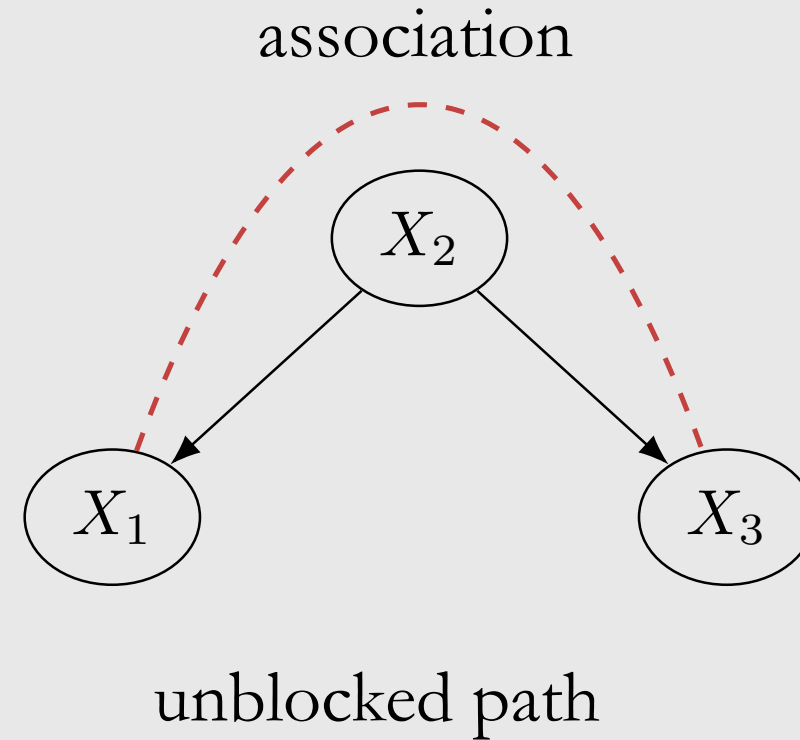
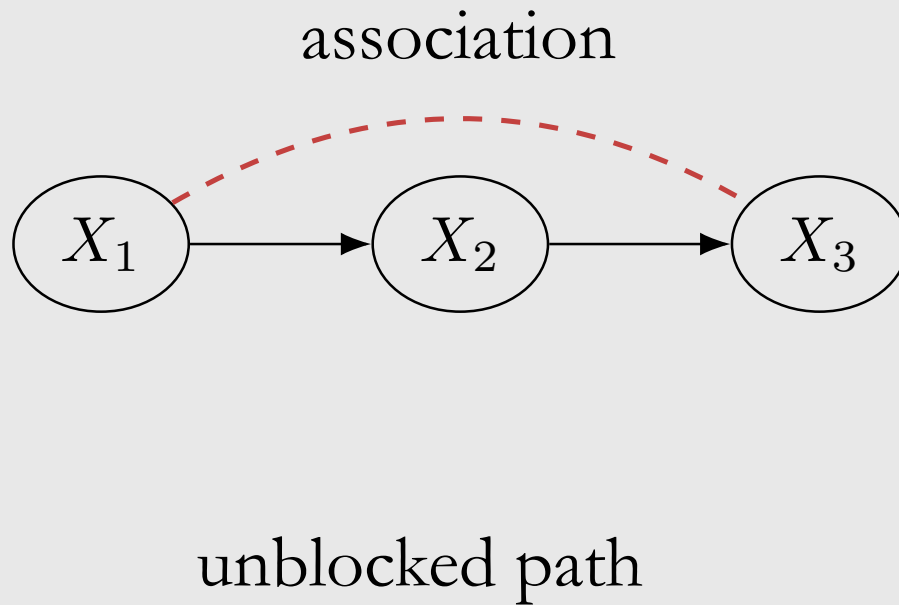
Chains and forks: independence



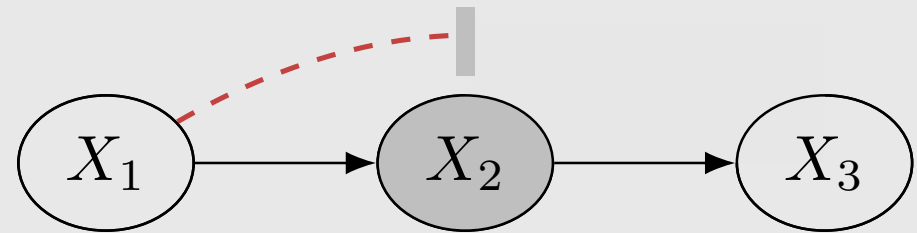
Chains and forks: independence



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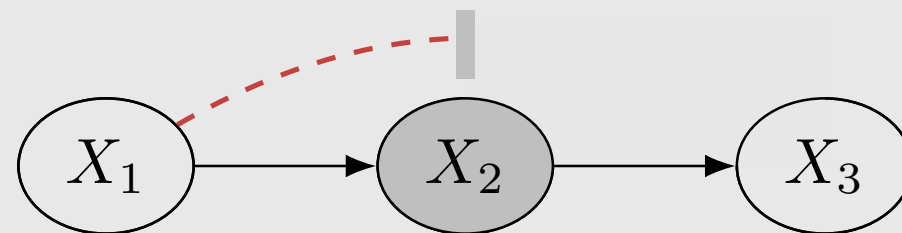


Proof of conditional independence in chains



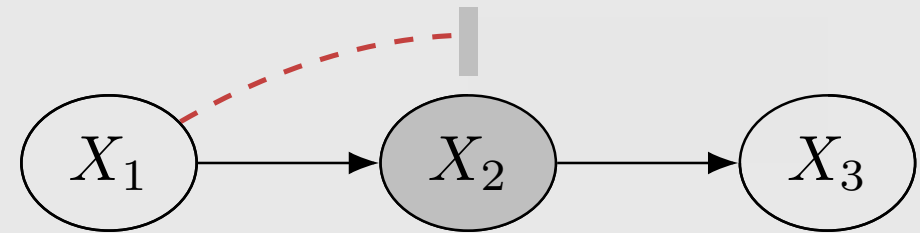
Proof of conditional independence in chains

Goal: show $P(x_1, x_3 \mid x_2) = P(x_1 \mid x_2) P(x_3 \mid x_2)$



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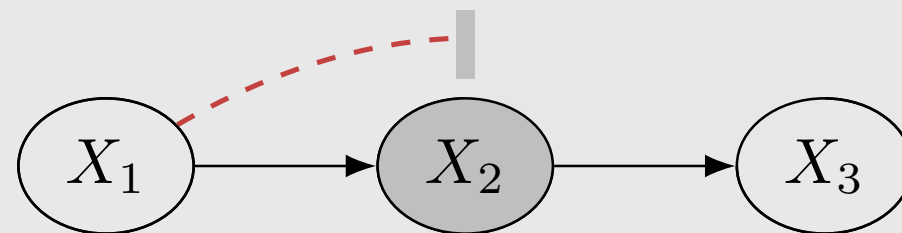
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1. Bayesian network factorization:

Proof of conditional independence in chains

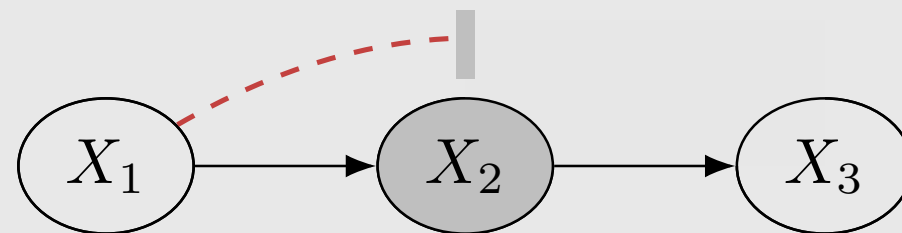
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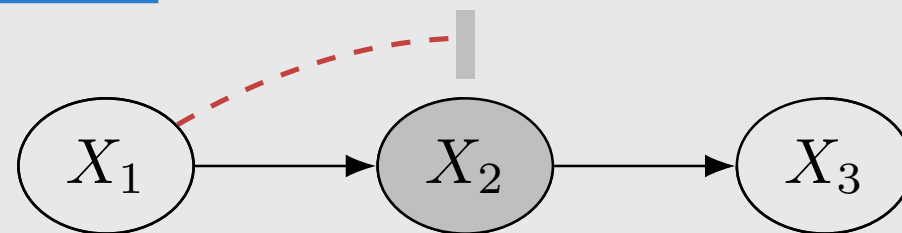


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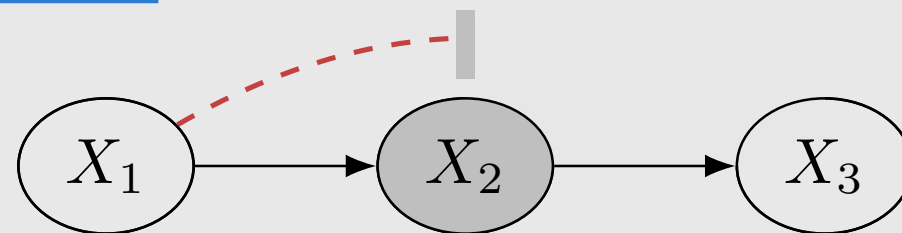


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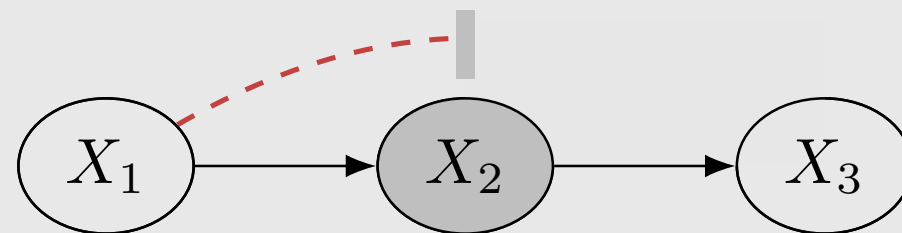


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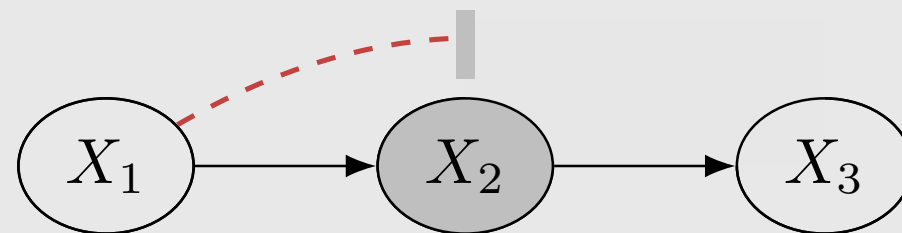
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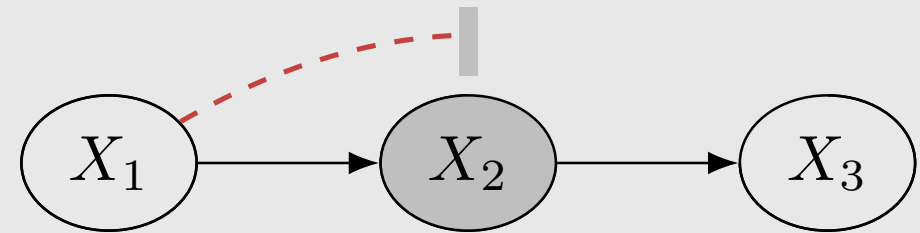
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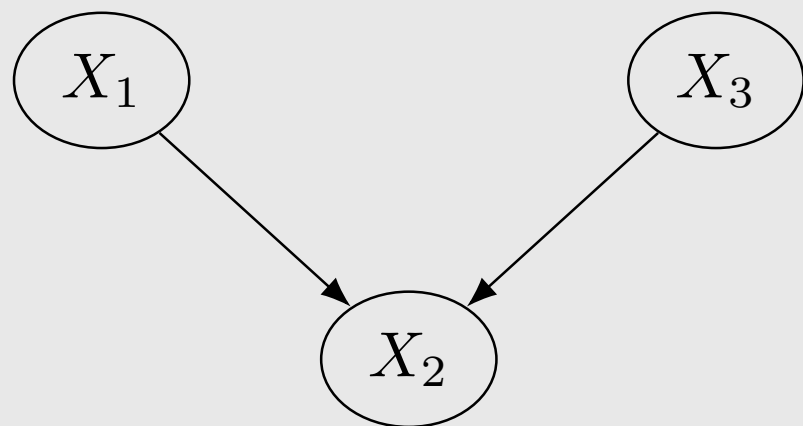
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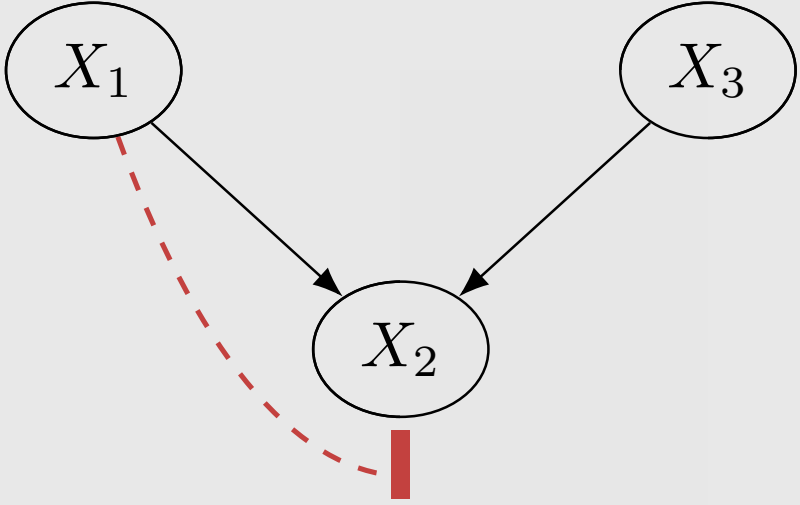
Proof of conditional independence in forks

Your turn 😊

Immoralities

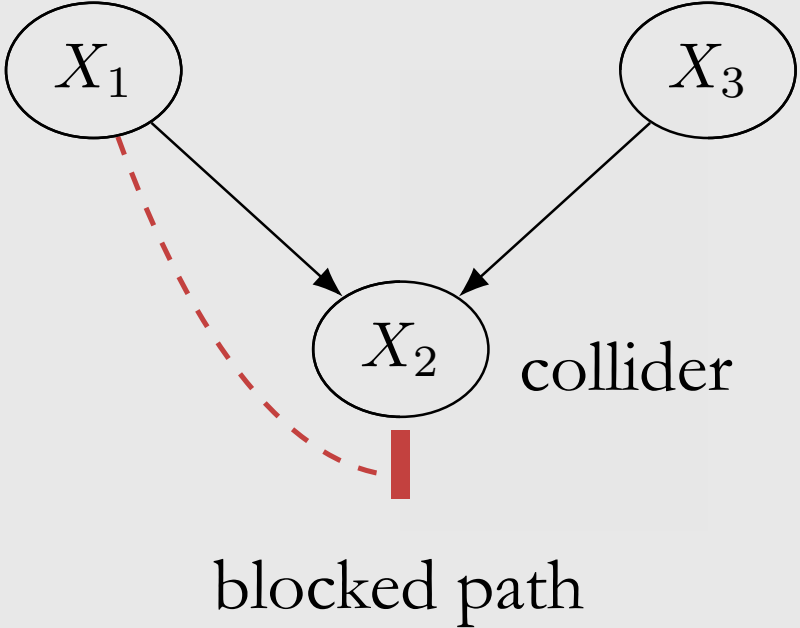


Immoralities

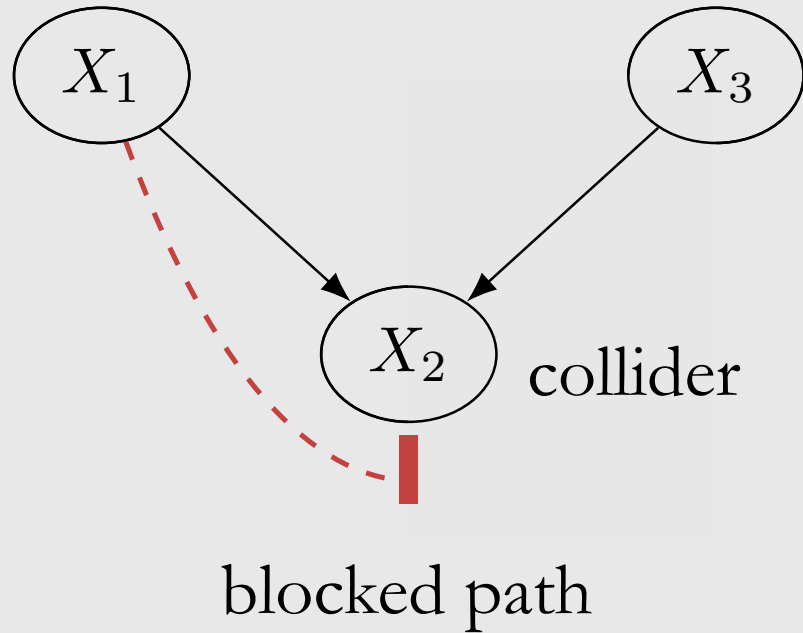


blocked path

Immoralities

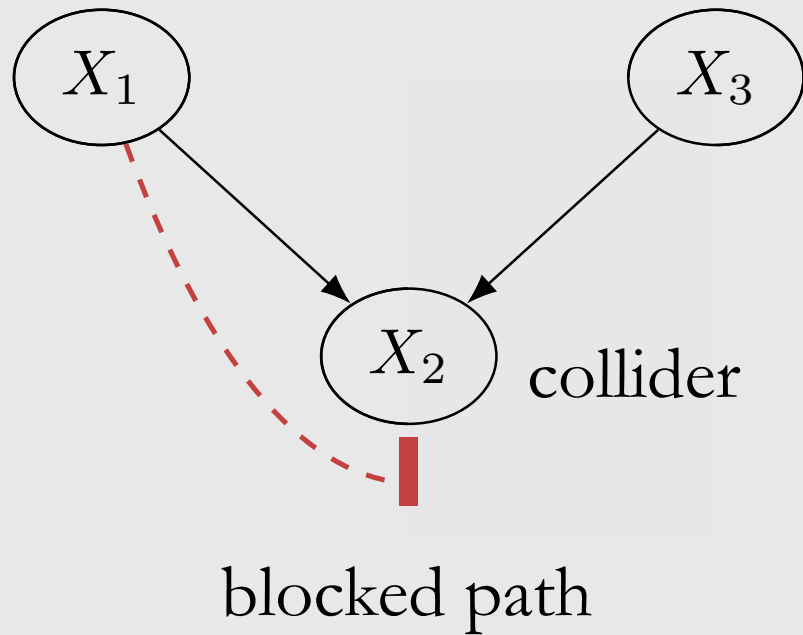


Immoralities



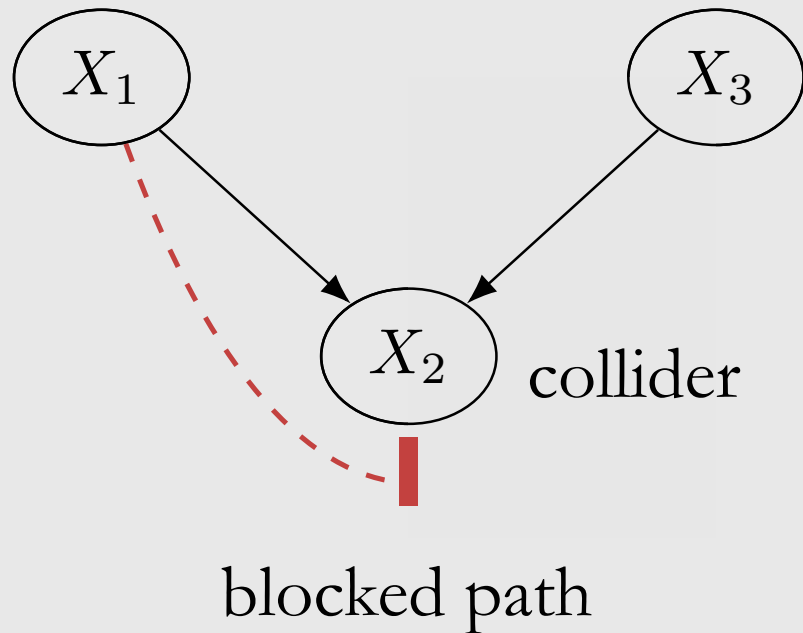
$$P(x_1, x_3) = \sum_{x_2} P(x_1, x_2, x_3)$$

Immoralities



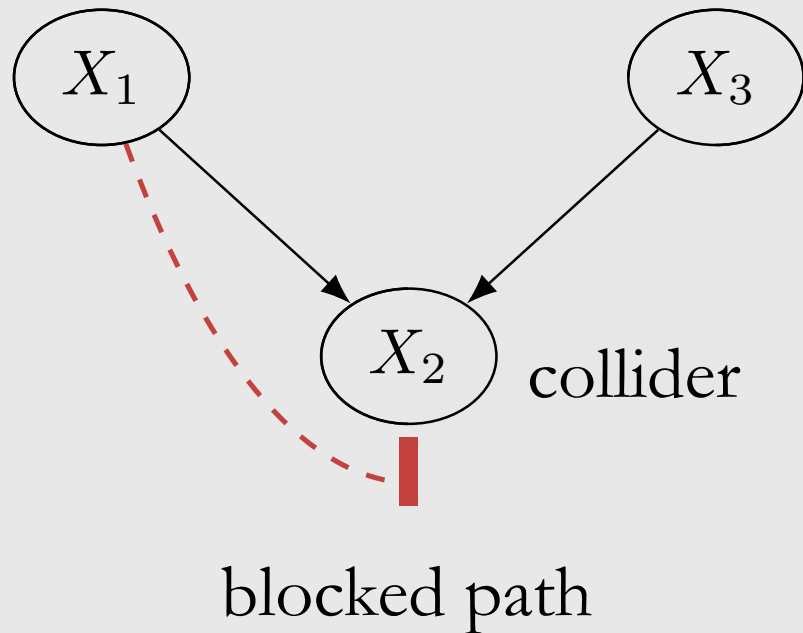
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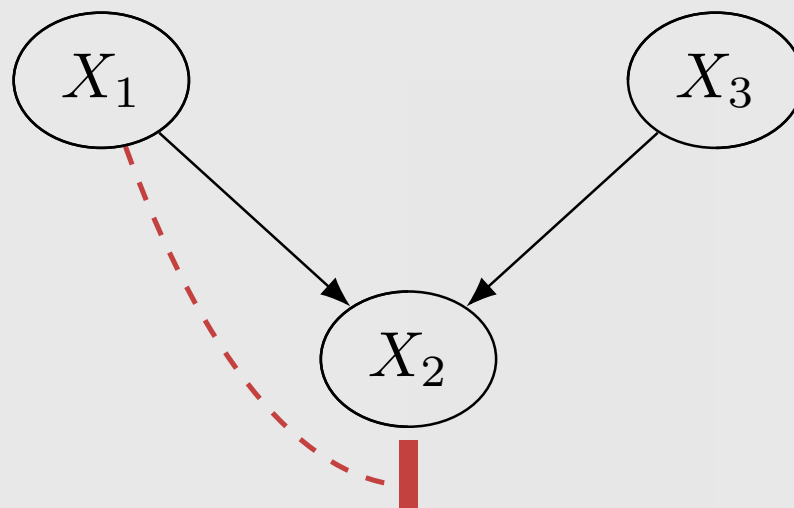
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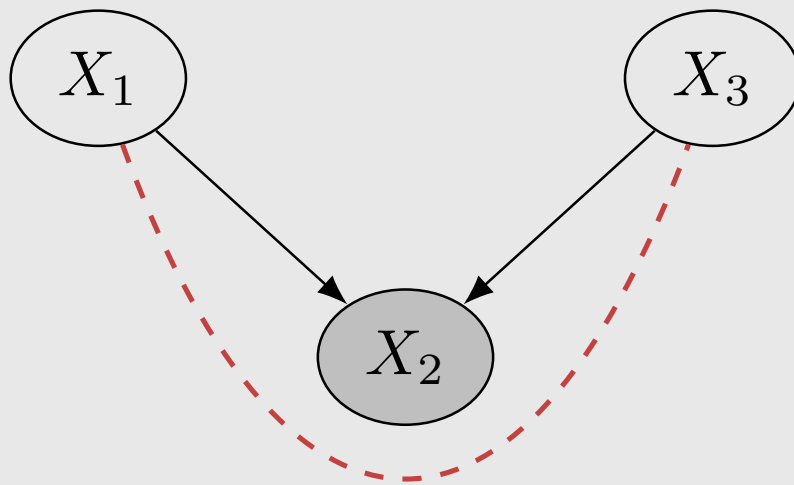
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Immoralities: conditioning on the collider



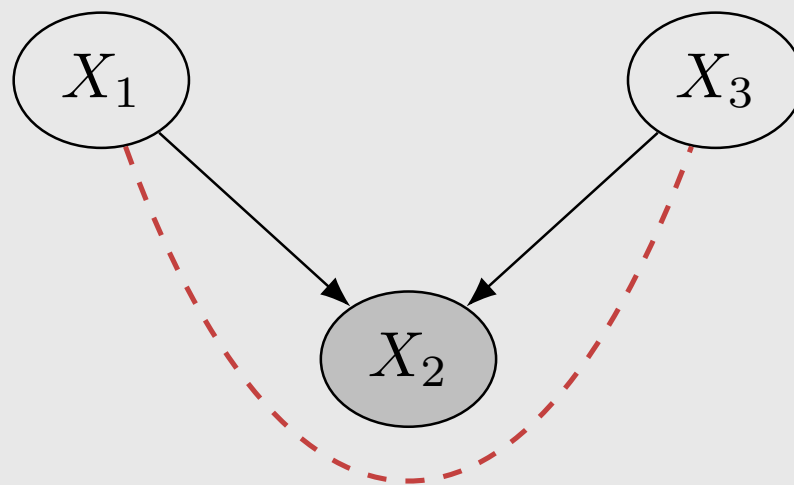
blocked path

Immoralities: conditioning on the collider



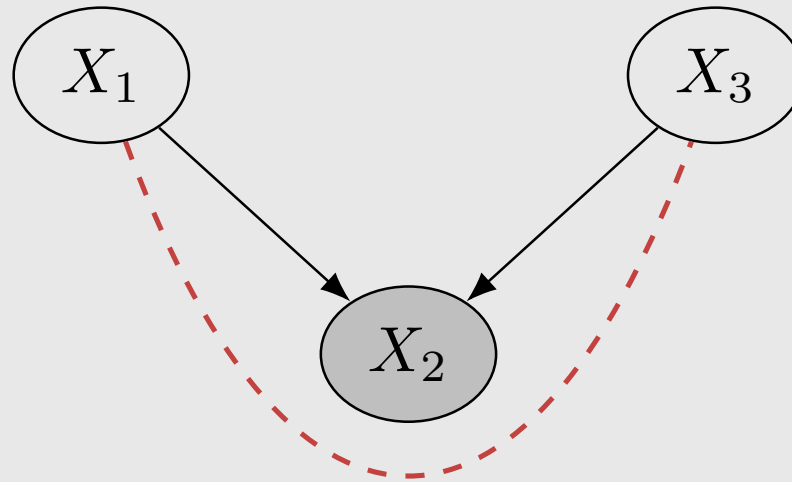
unblocked path

Example: good-looking men are jerks



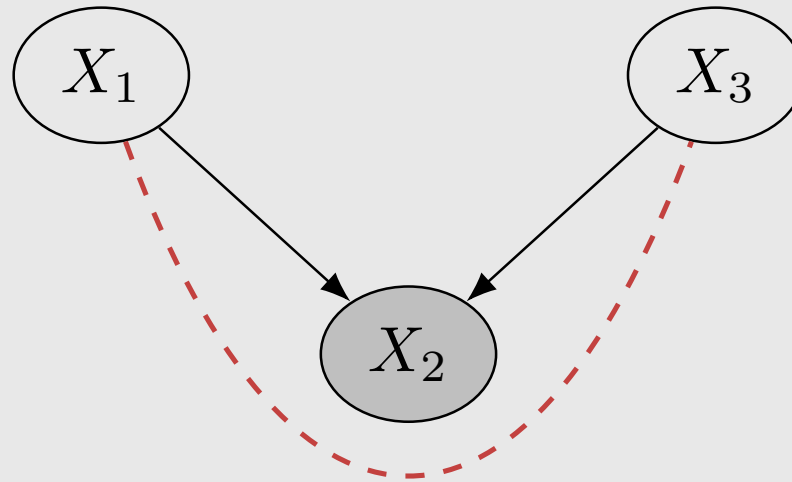
Example: good-looking men are jerks

$$X_1 = \begin{cases} 1 & \text{good-looking} \\ 0 & \text{otherwise} \end{cases}$$



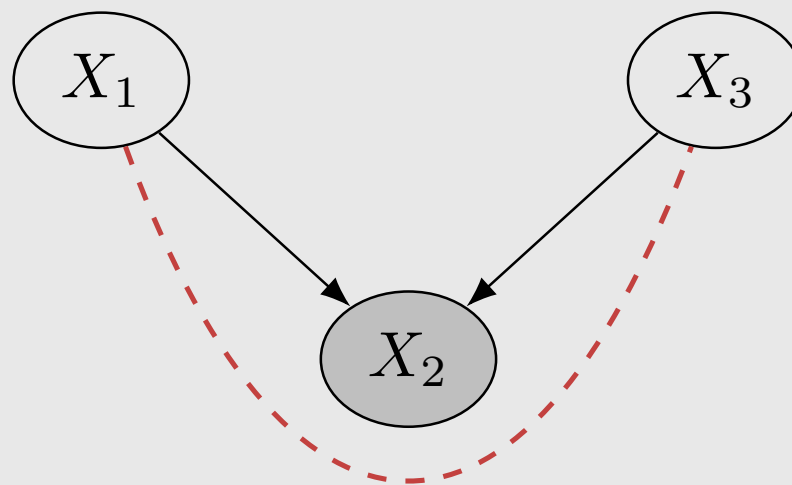
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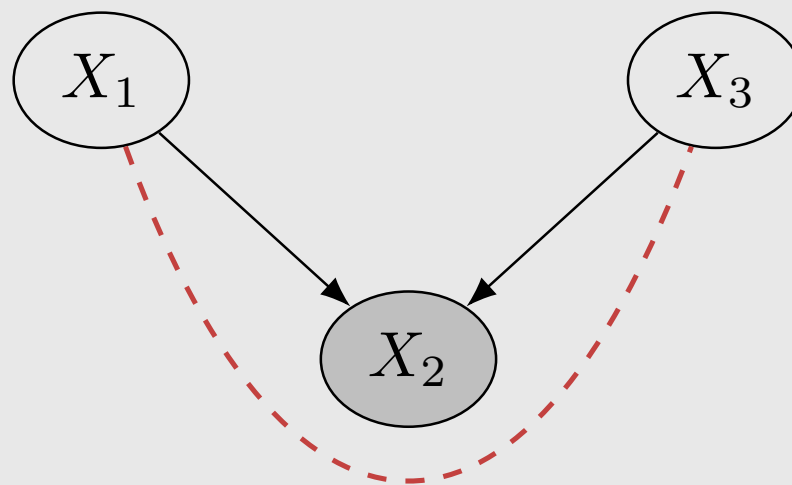
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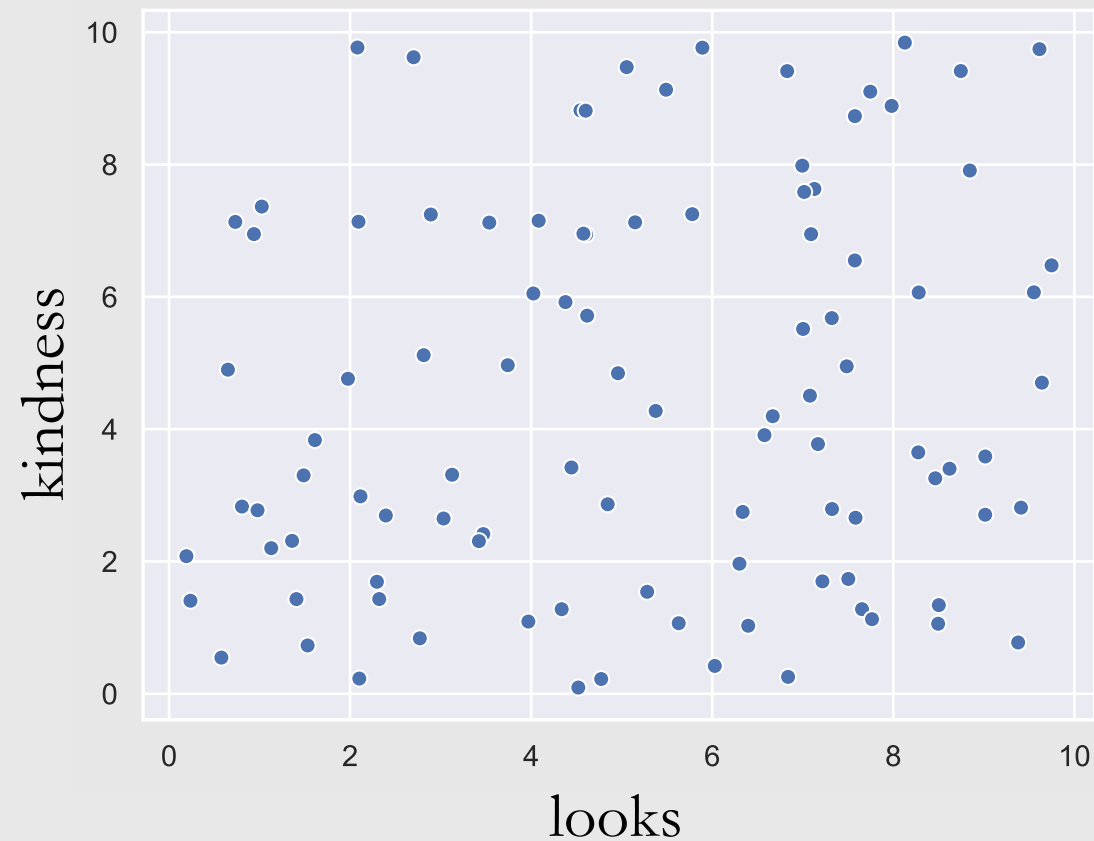
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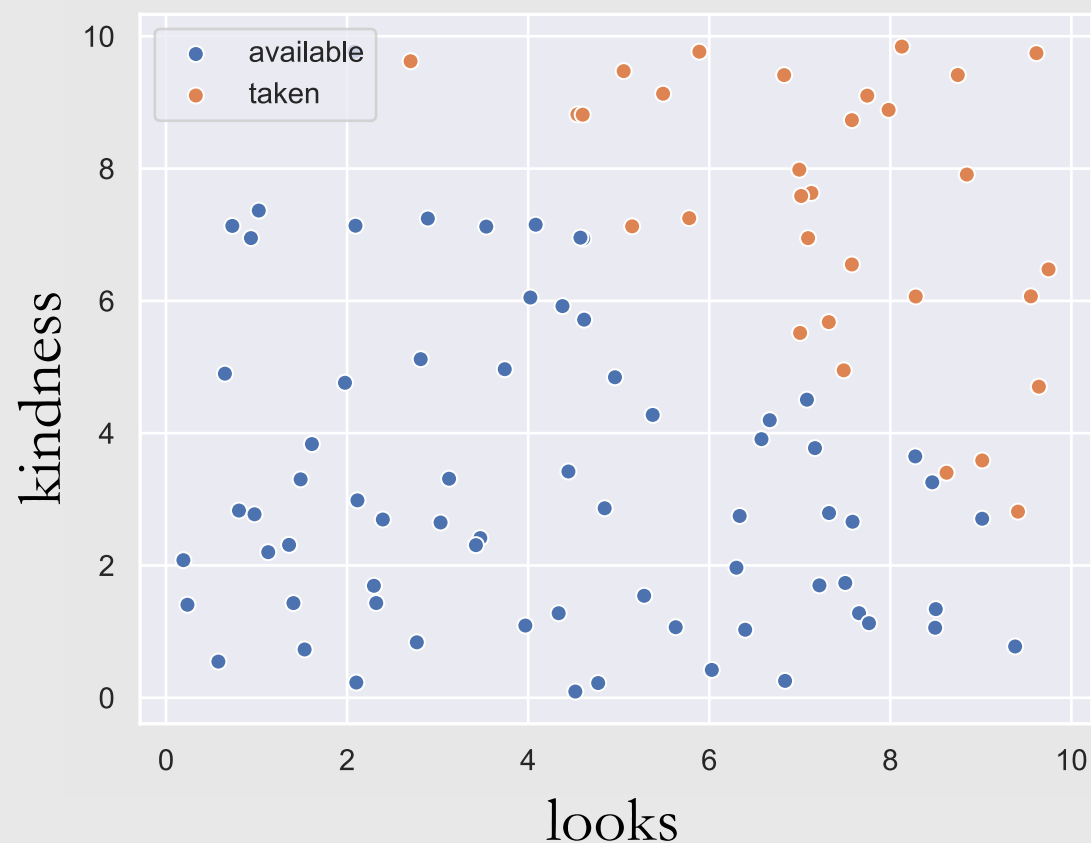
Good-looking men are jerks scatterplot

Full population



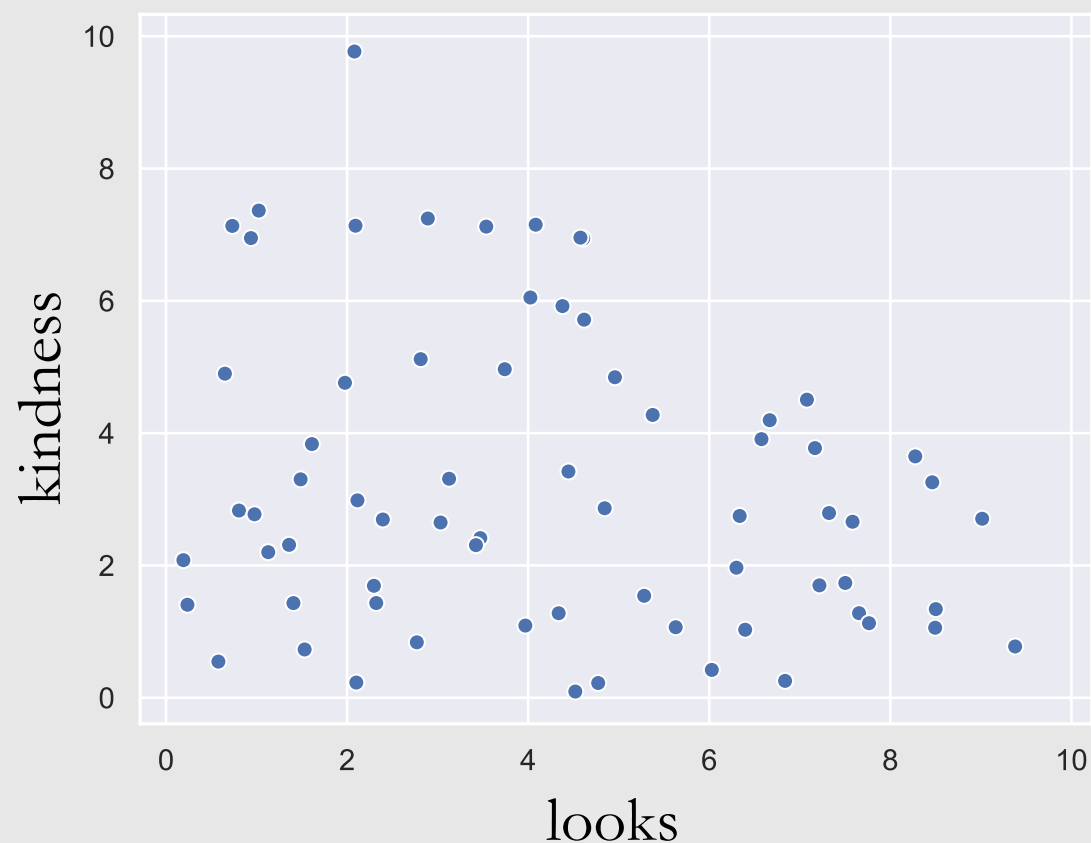
Good-looking men are jerks scatterplot

Groups by availability

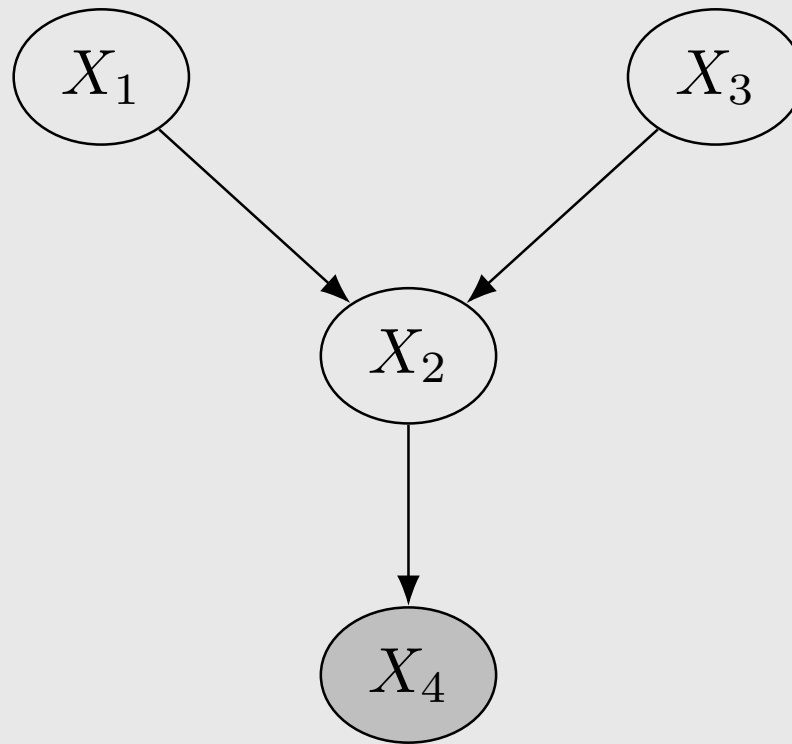


Good-looking men are jerks scatterplot

Available men

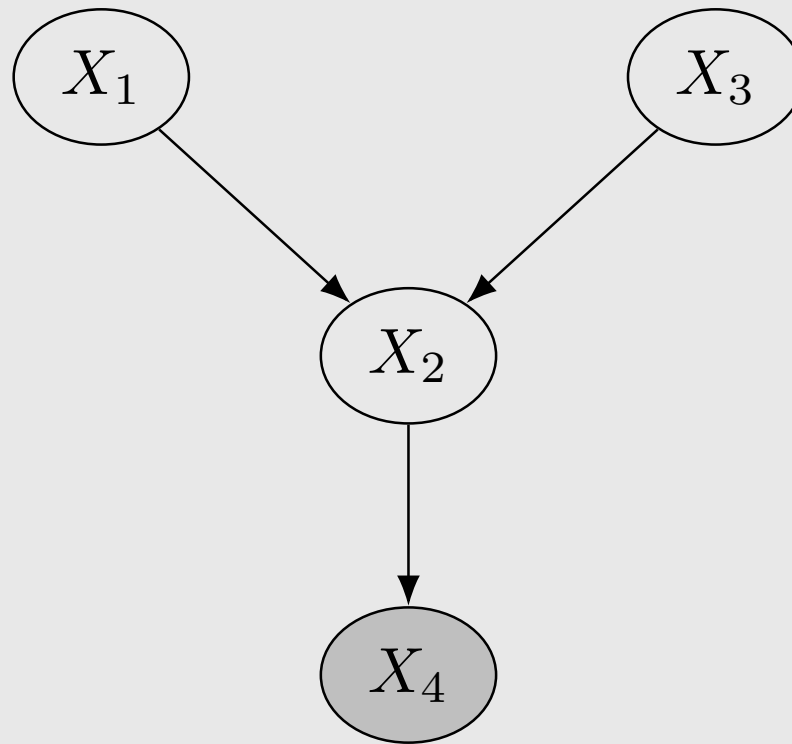


Conditioning on descendants of colliders



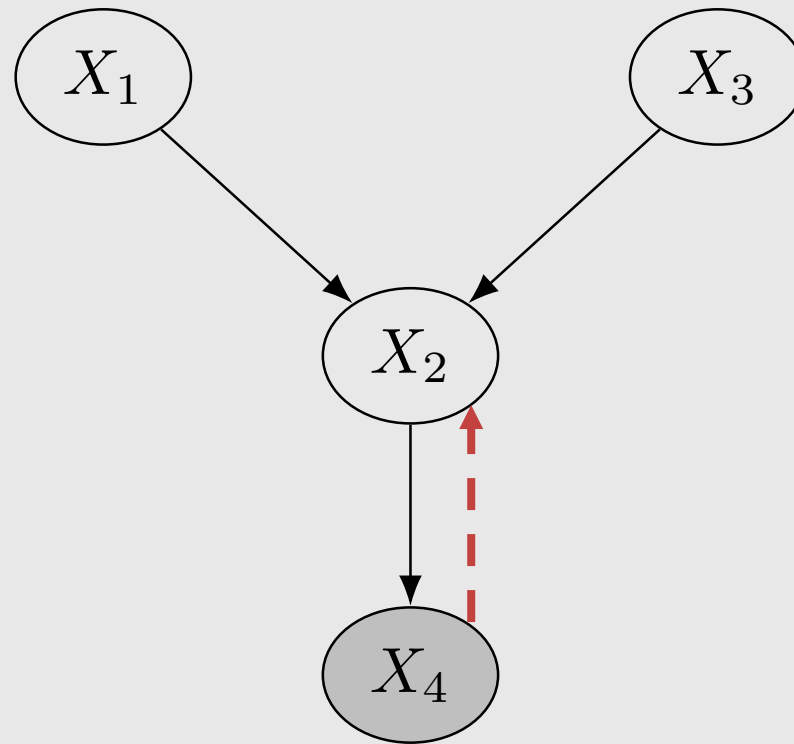
Conditioning on descendants of colliders

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Conditioning on descendants of colliders

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Question:

In the three different kinds of three-node graphs, what can block a path?

Graph terminology

Bayesian networks and causal graphs

The basic building blocks of graphs

The flow of association and causation

Blocked path definition

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Unblocked path: a path that is not blocked

d-separation

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Two (sets of) nodes X and Y are d-separated by a set of nodes Z if all of the paths between (any node in) X and (any node in) Y are blocked by Z .

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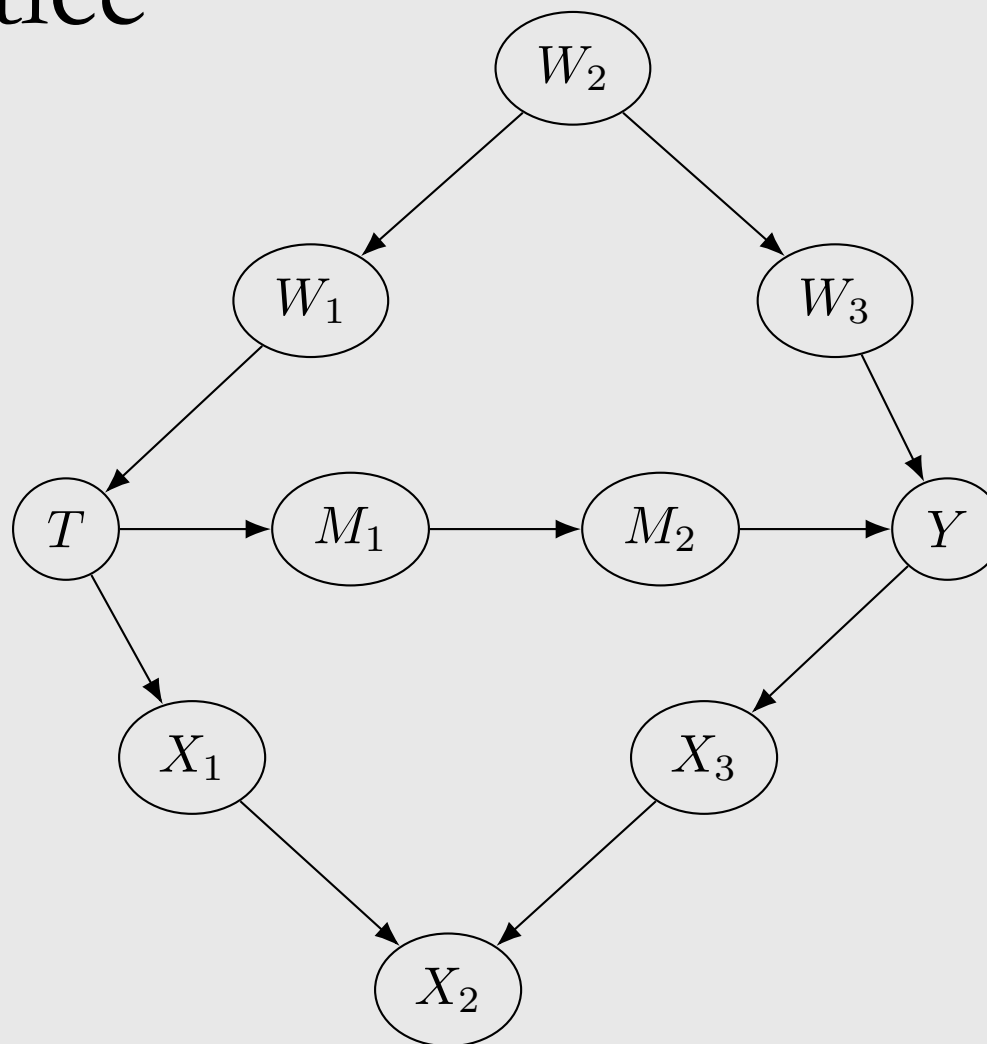
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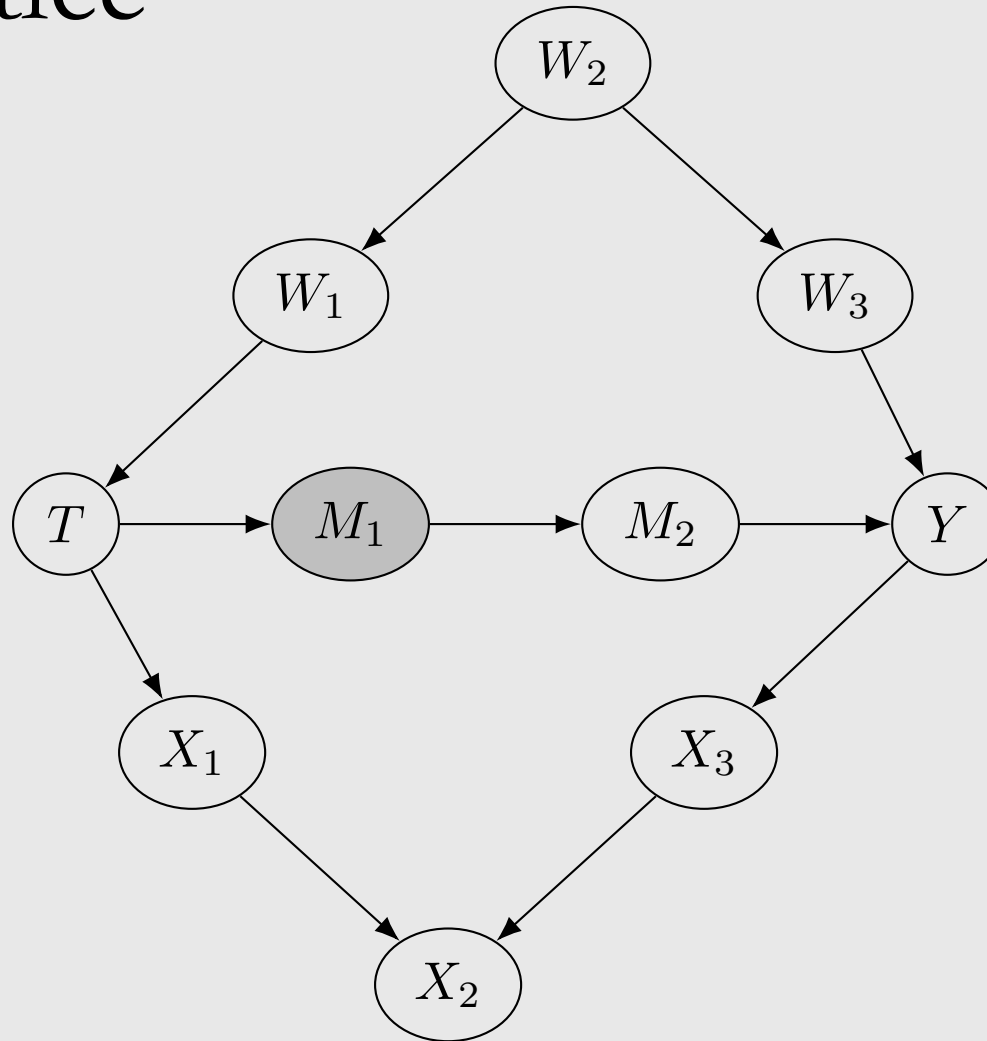
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Markov assumption

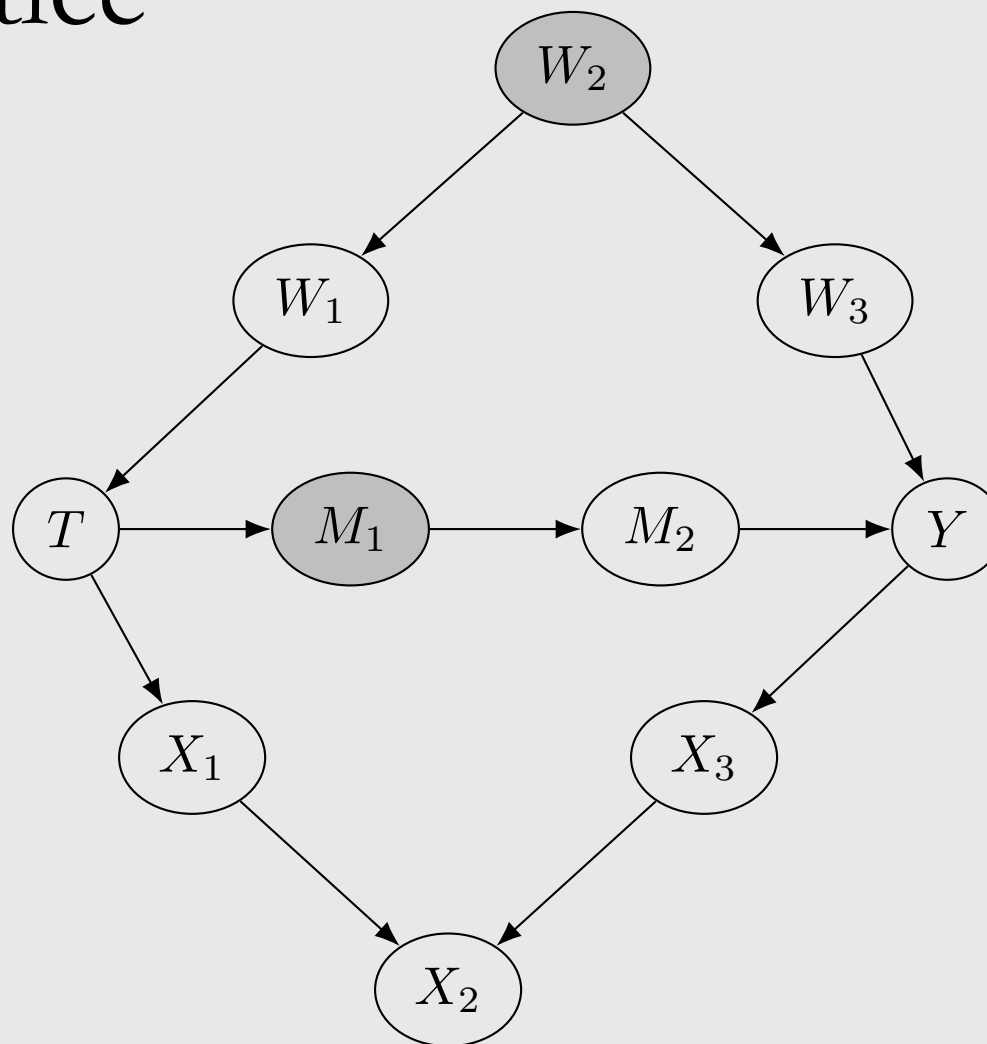
d-separation practice



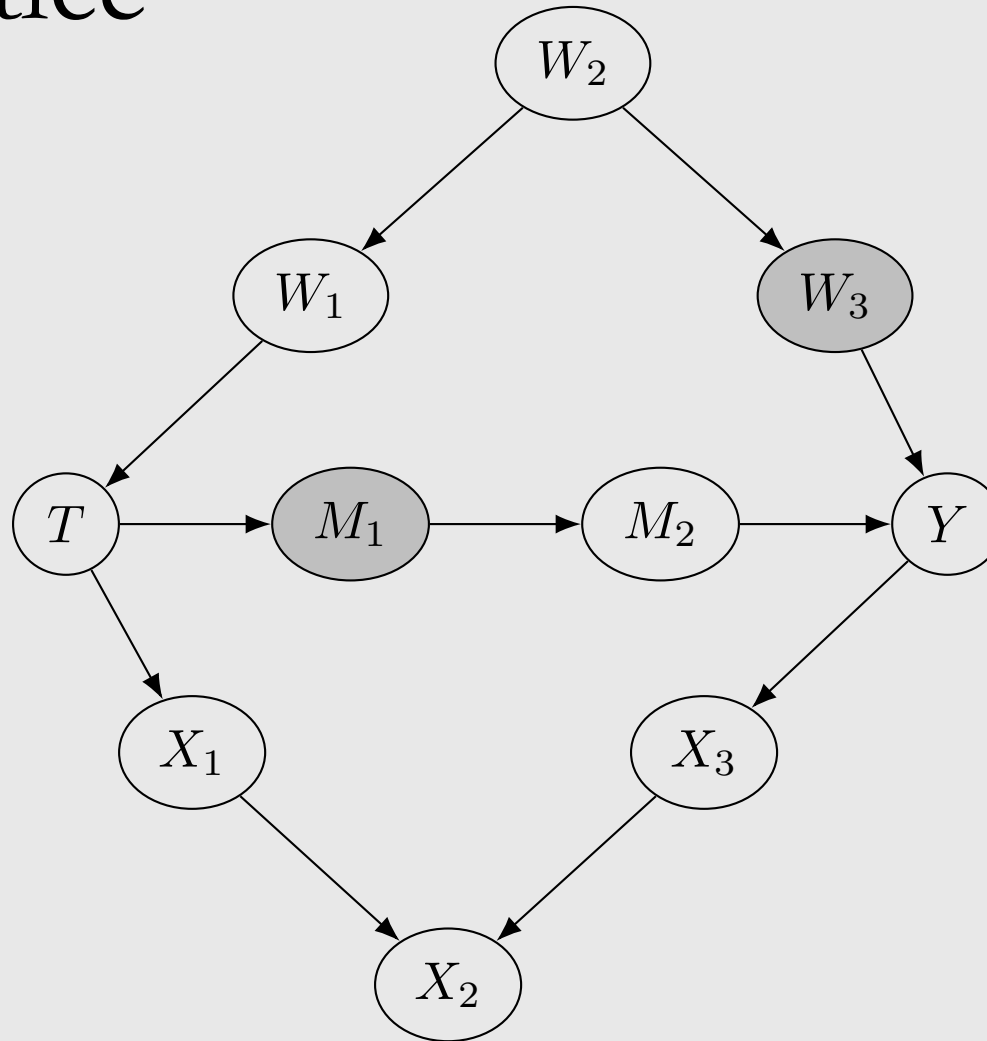
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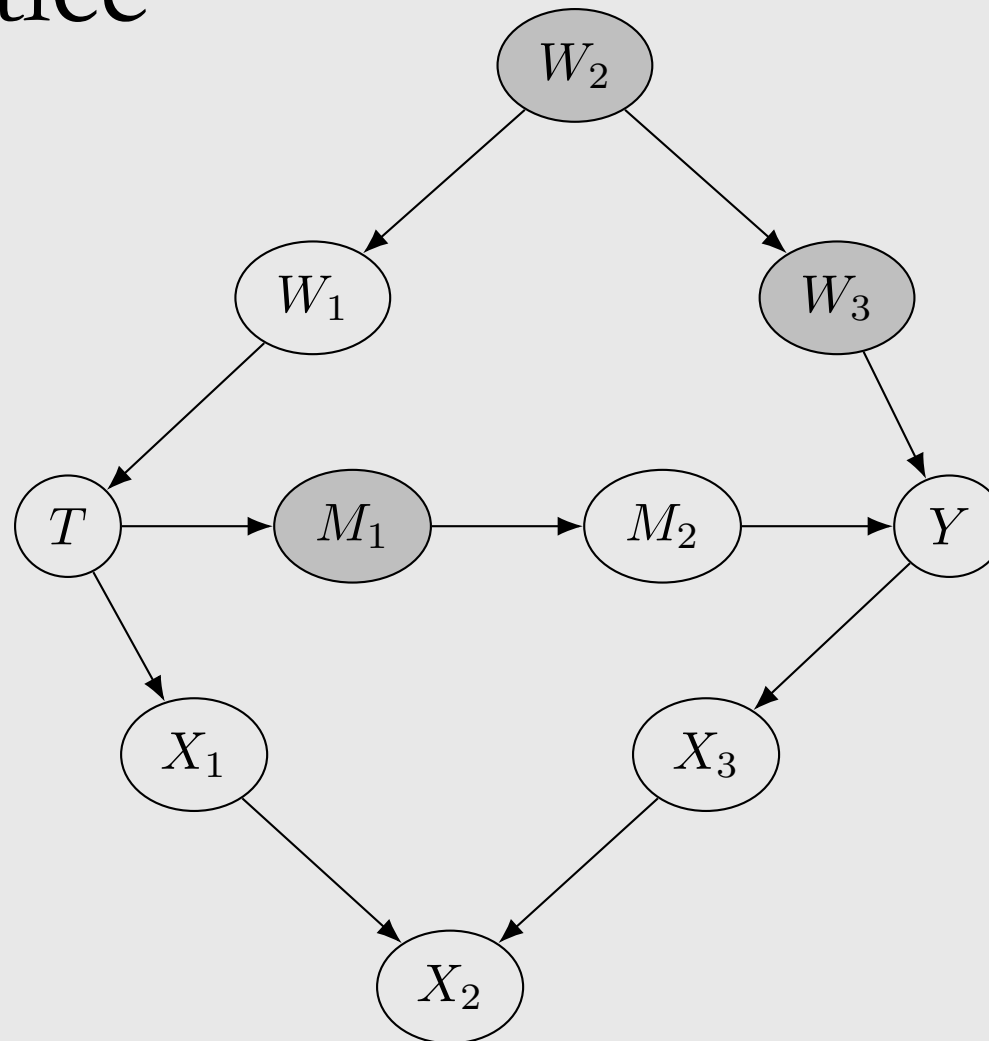
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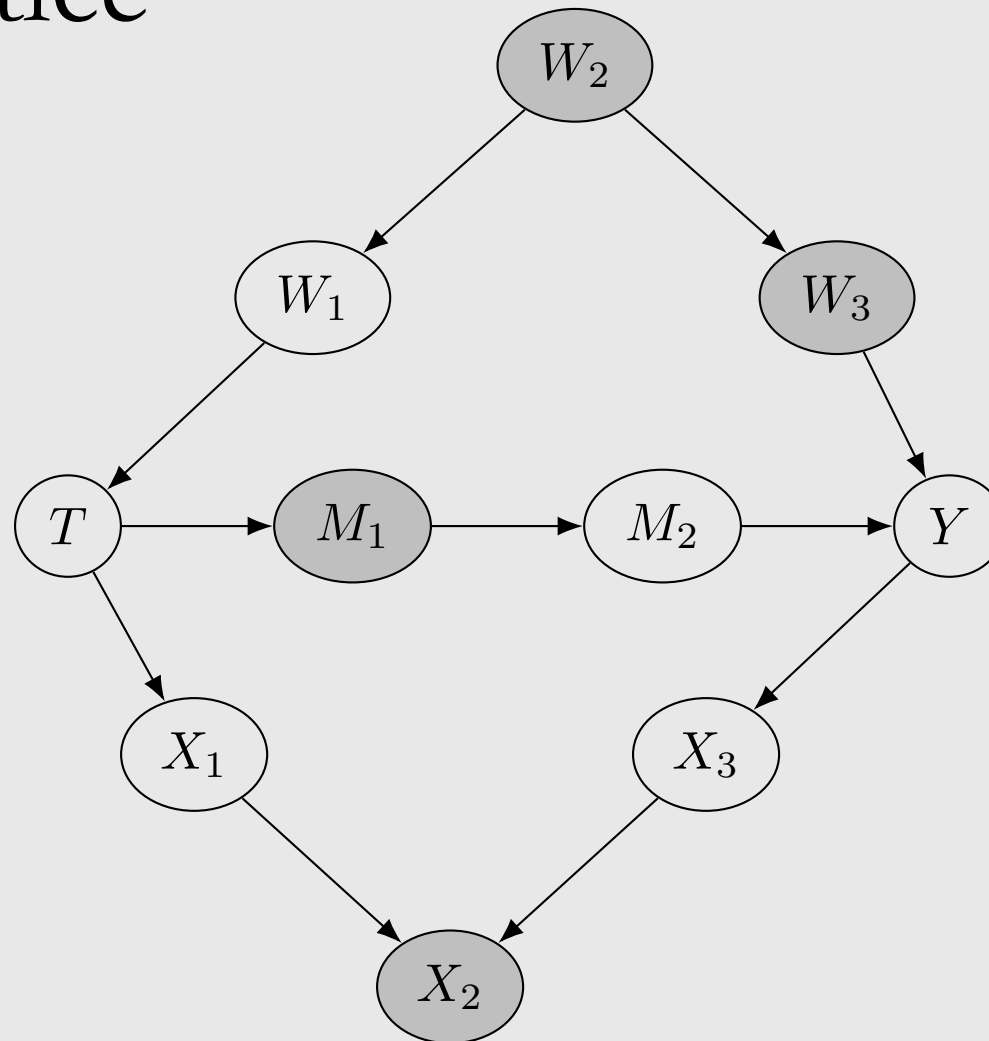
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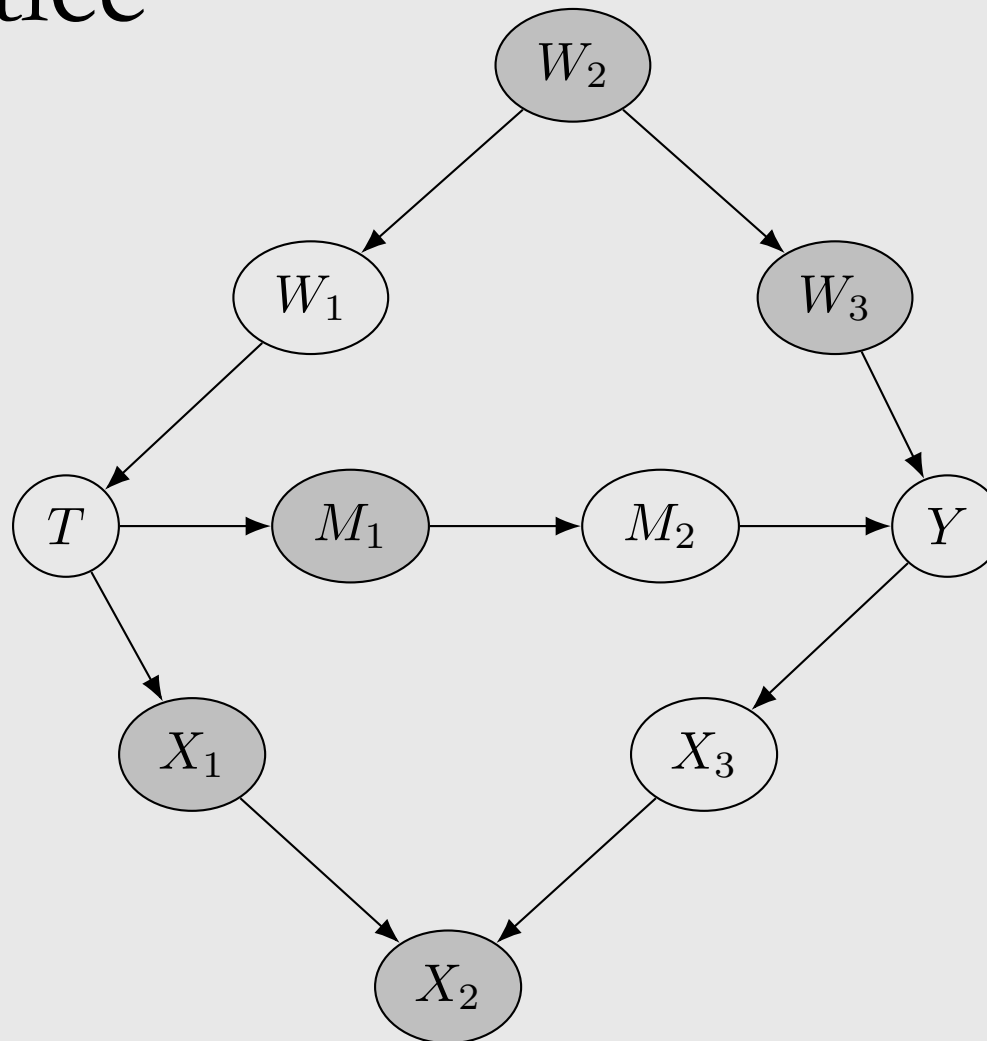
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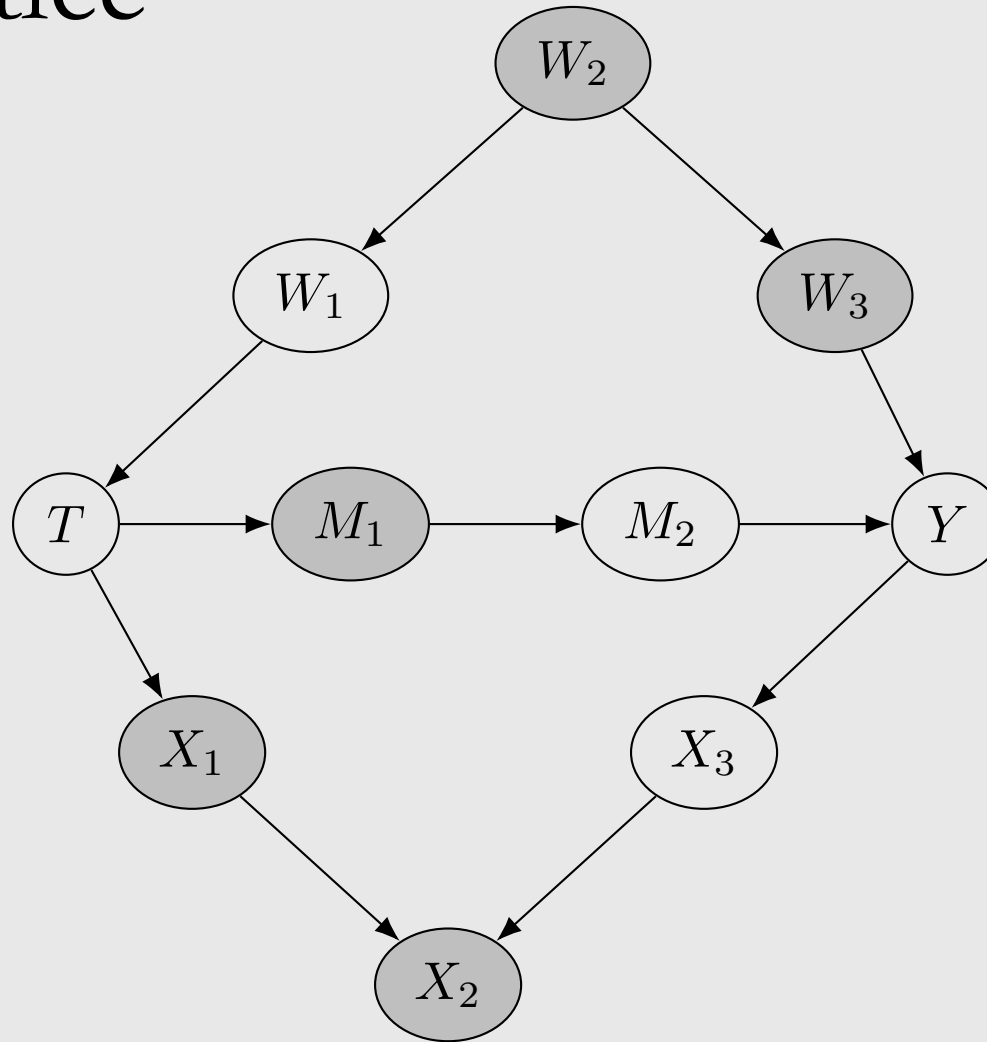
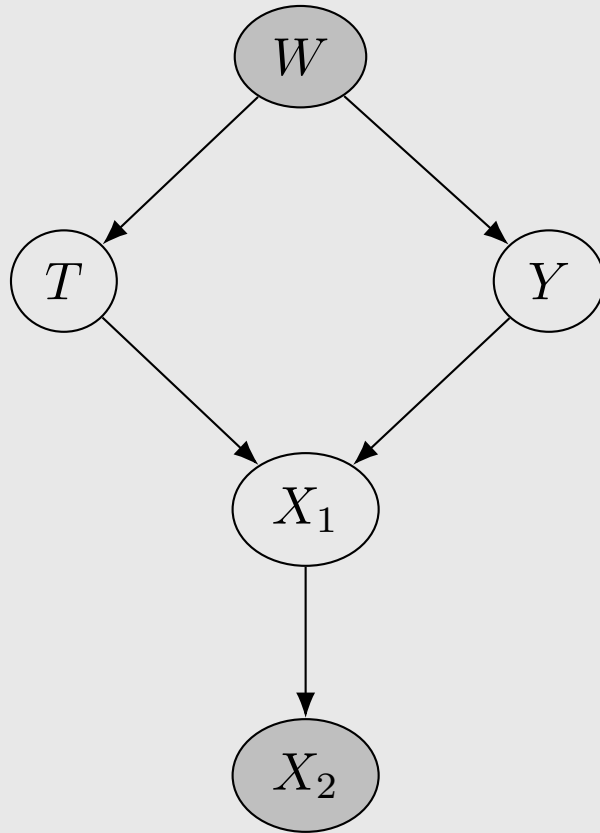
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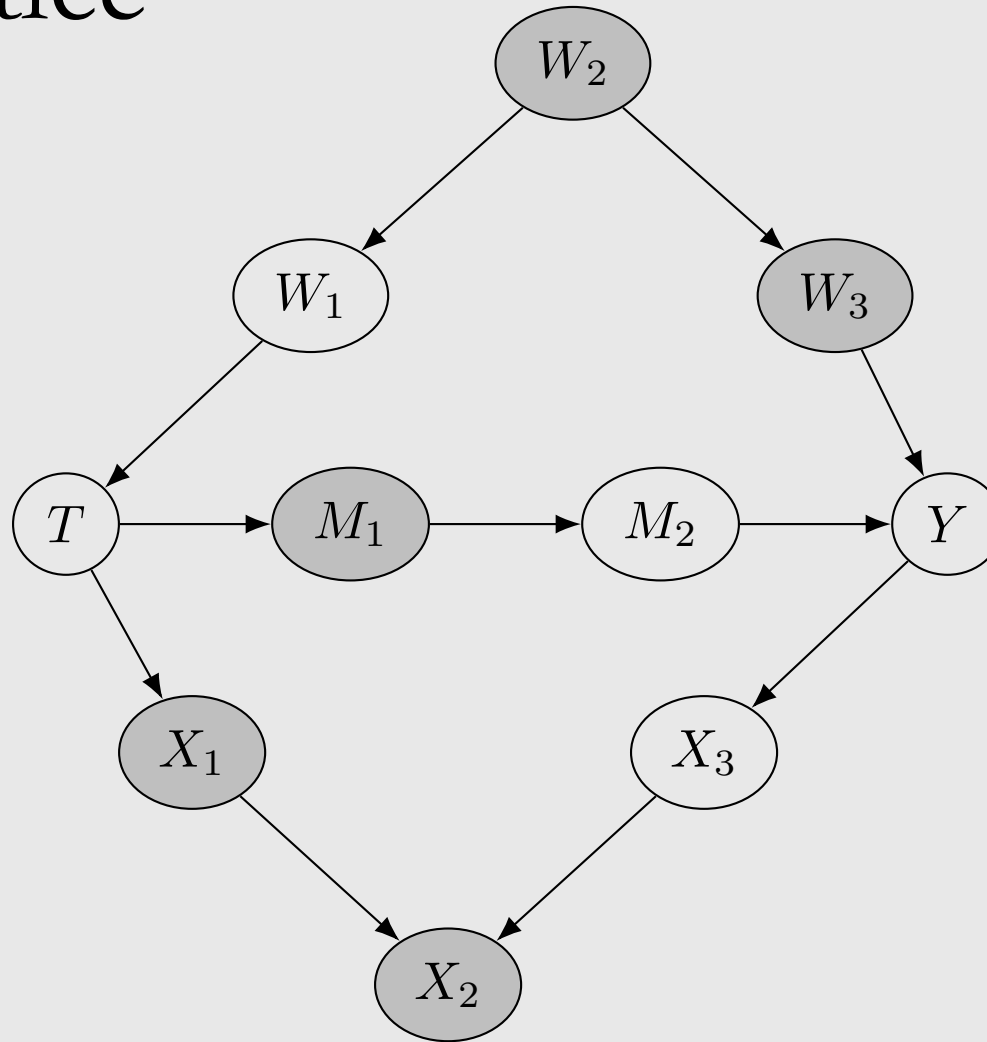
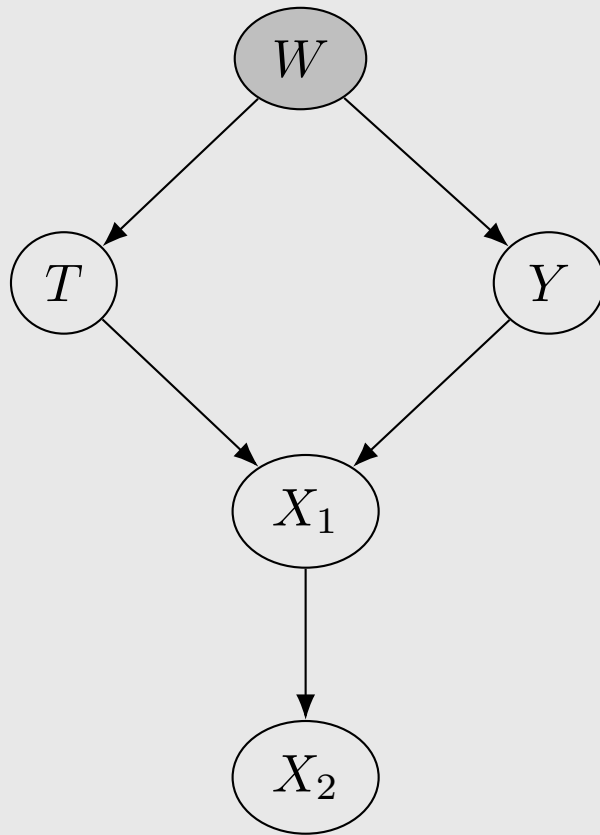
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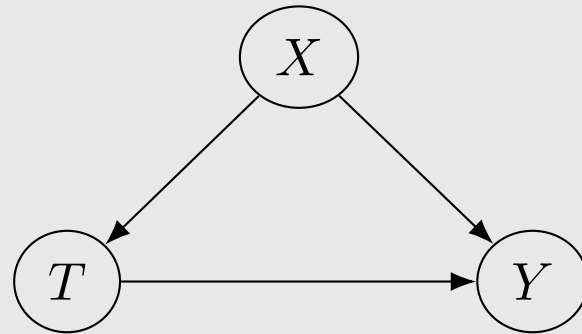
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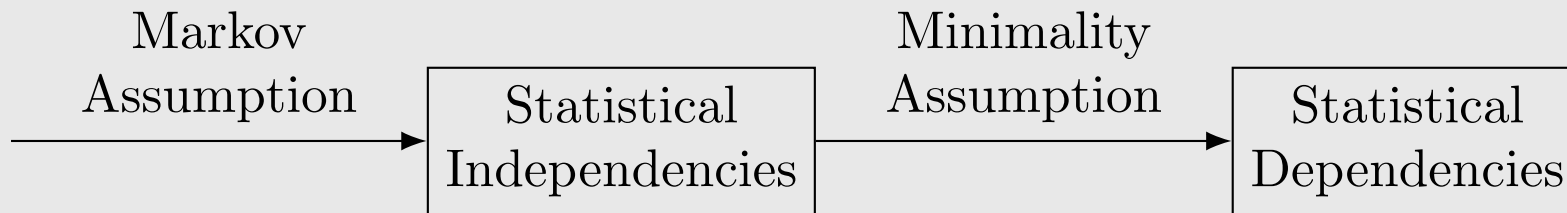
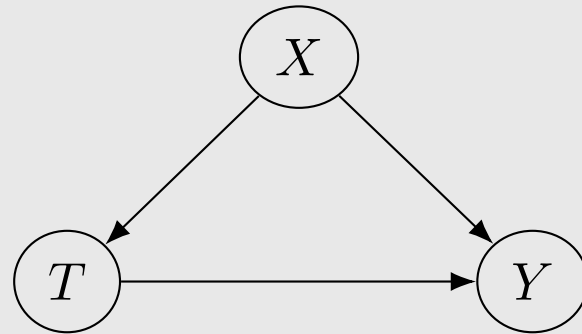
d-separation practice



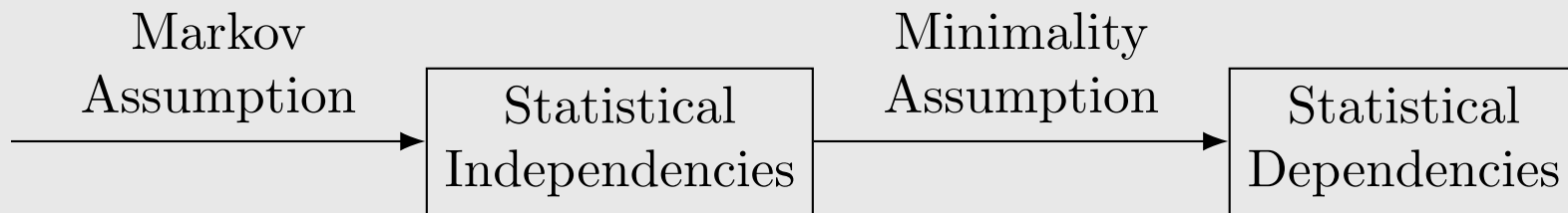
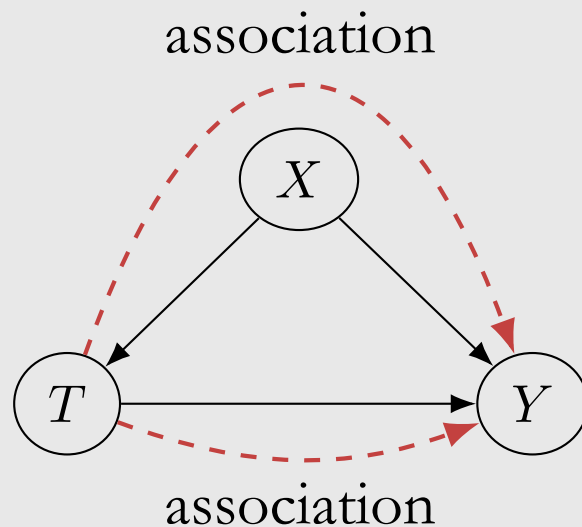
The flow of association and causation



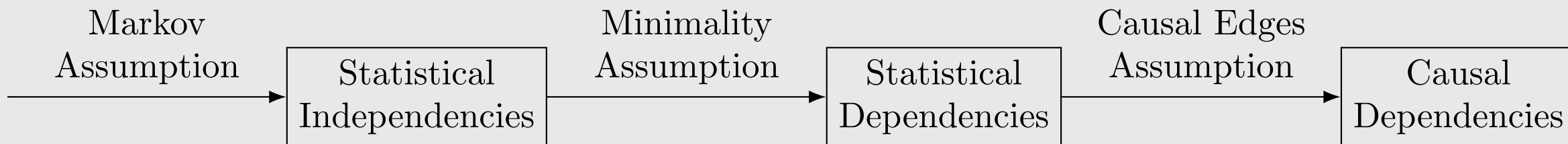
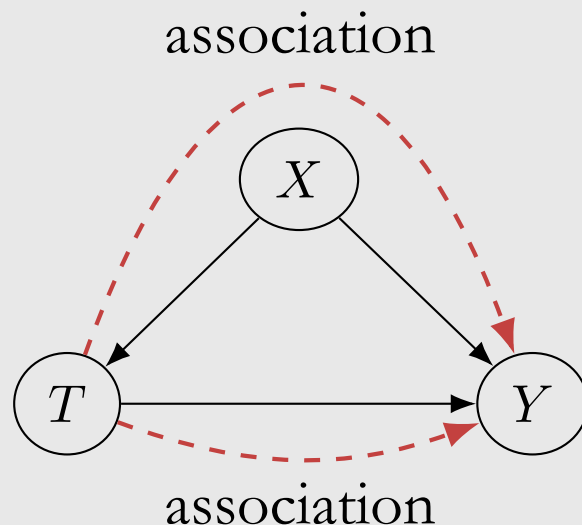
The flow of association and causation



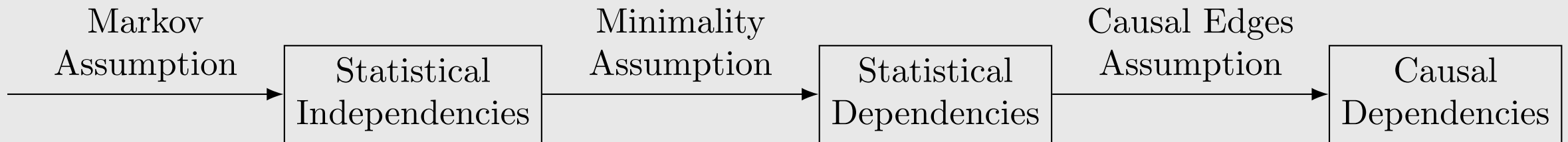
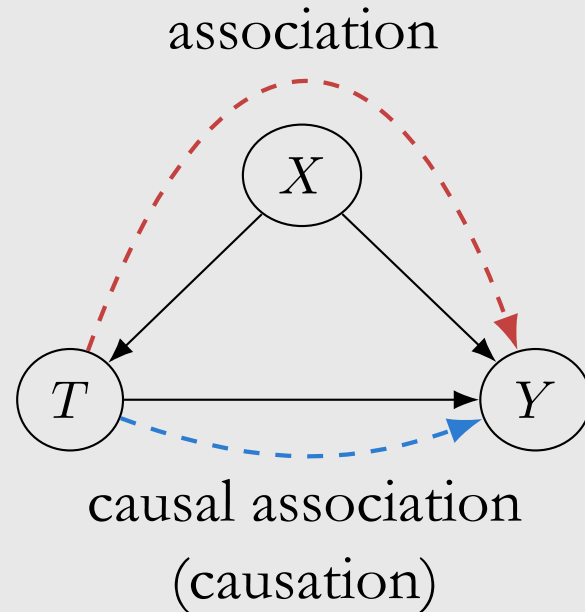
The flow of association and causation



The flow of association and causation



The flow of association and causation



The flow of association and causation

